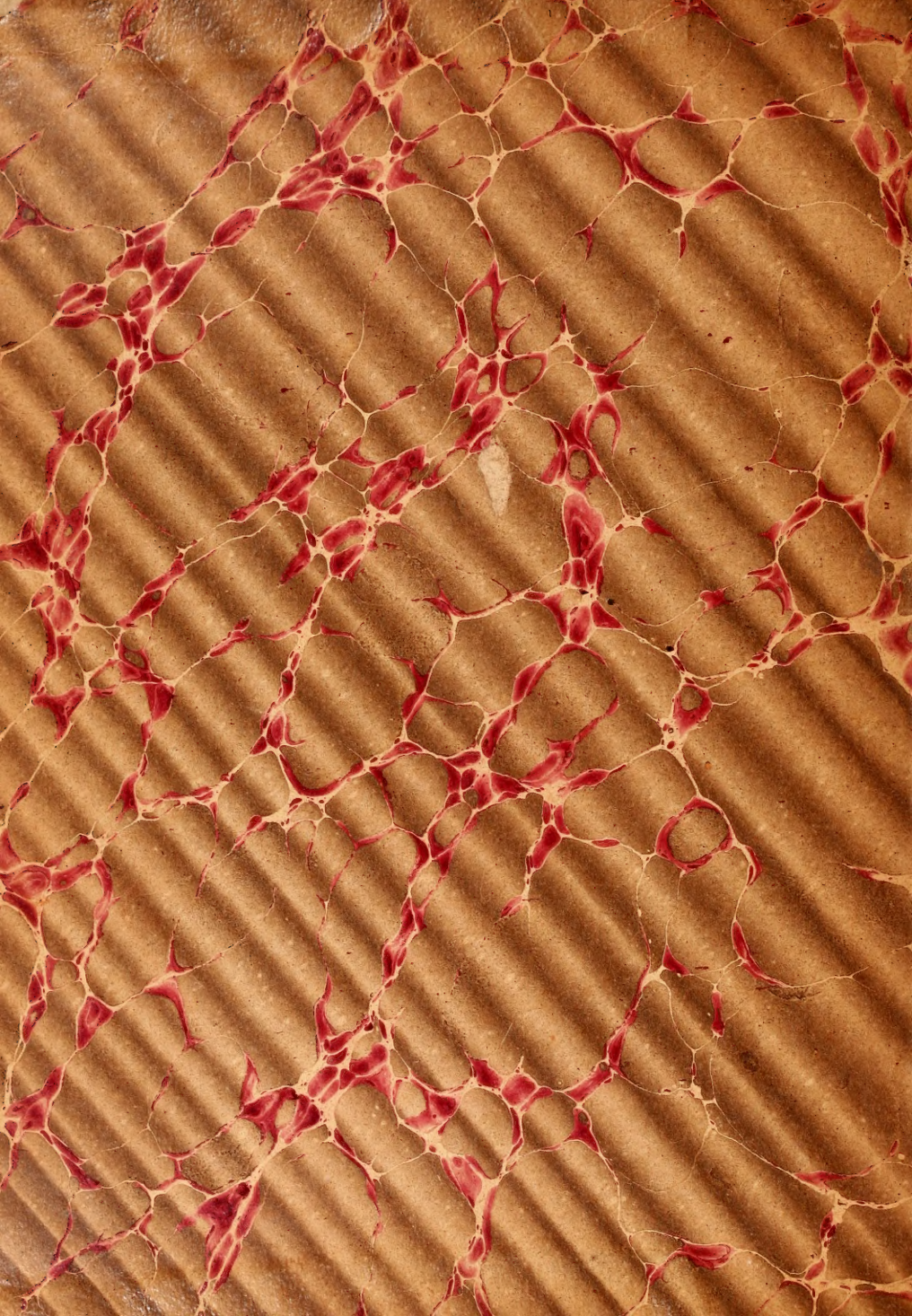
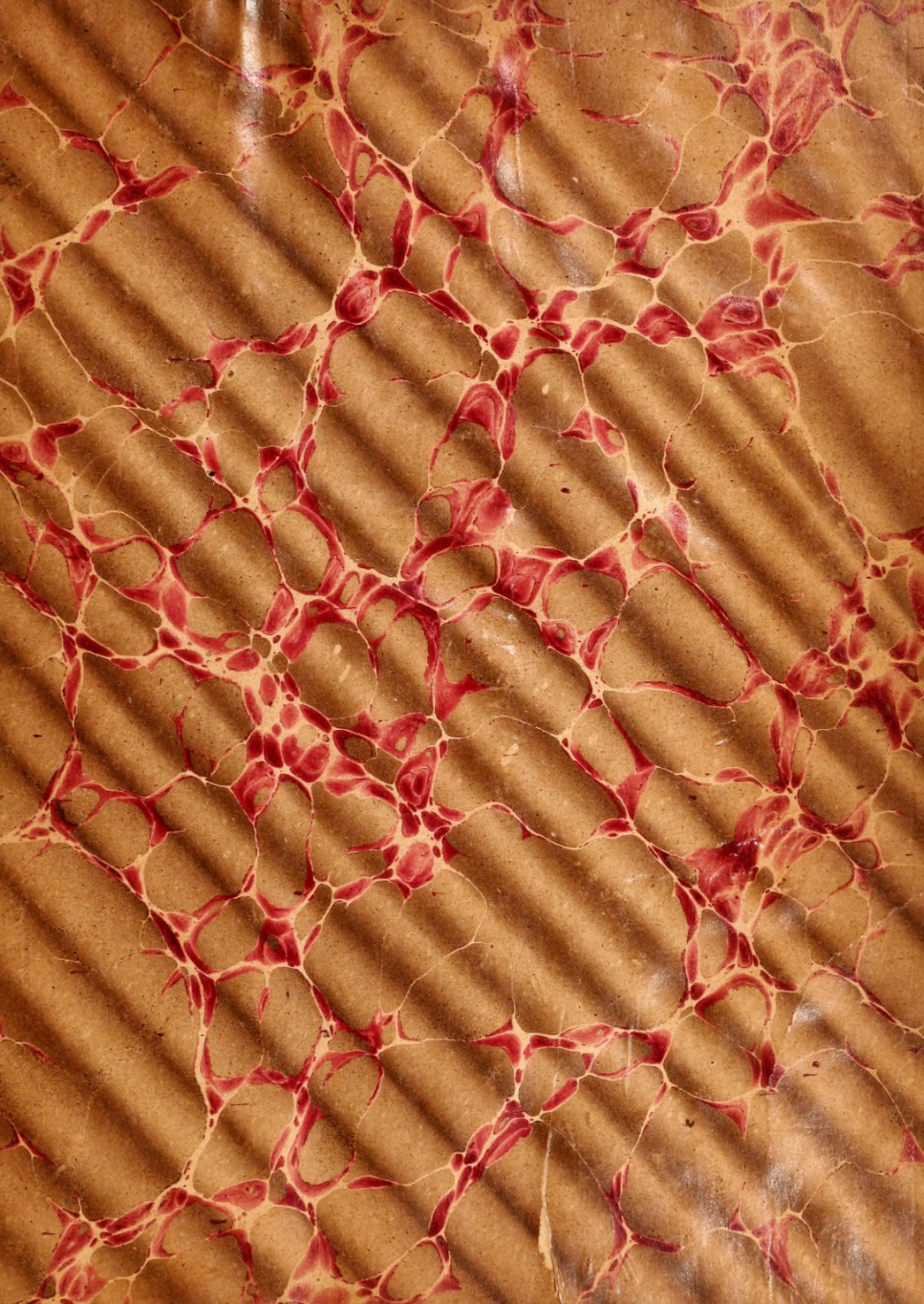


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On a Complete System
of Invariants of Two Triangles.
by
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submitted to the Board of
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On a Complete System of Invariants of Two Triangles.

Introduction.

The simpler invariants of two triangles are derived from the covariants set up ^{by} them, when regarded as two cubic curves of the third order and of the third class respectively, have been discussed at length by Dr. Sturm.*

The system there derived is obviously incomplete as is pointed out in the article. The present paper seeks to present a complete system, by means of which the invariant relations can be conveniently expressed. Some additional

* Transactions American Math Soc. Vol. 7, No. 1, p. 37 ff.

is also given to a few of the covariants but no exhaustive treatment has been attempted.

In developing the system of invariants proposed in the present paper the following was found, simplified even to the most gradual. The fact that the particular problem which to a large extent gave rise to this paper was first proposed by Prof. Mealy, viz. What is the invariant relation between two triangles so that a circle may be drawn on the vertices of one triangle and touch the sides of the other? This problem will be discussed in a subsequent chapter. In this way the selection of the present system of invariants was largely a matter of experiment

and observation the object of course
being to select such as would enable one to write down invariant
relations in the most simple form,
and at the same time, to have the
fundamental concepts themselves
as easily interpreted geometrically as
possible. In the original solution
of these special problems one triangle
was invariably taken as the refer-
ence triangle and the invariant
relations were consequently expressed
in terms of the coefficients of the
other. Naturally in most instances
of the same simplification in much
of the discussion following.

It has, however, seemed advisable
in this paper to follow what may
be termed the historical, and at the
same time more logical order, and to

begin by giving the measurements in
their most general form. These
were obtained in the first place
from the simplified forms very
rapidly, as soon as the latter and
their interrelations were known.

§1. The Primary System.

Take the one triangle as a 3-line in the most general symbolic form

$$(\alpha x) (\beta x) (\gamma x) = 0,$$

and the other as a 3-point

$$(a \xi) (b \xi) (c \xi) = 0$$

where the expressions in parentheses are the ordinary, symbolic coordinates, i.e.

$$(\alpha x) = \alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_3, \text{ etc.}$$

A system of invariants which we will use and later prove to be a complete system is the following:—

$$1) \quad \Delta_1 = \begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix}$$

$$2) \quad D_1 = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}.$$

$$3) \quad I_1 = (a_1)(b_2)(c_3) + (a_2)(b_3)(c_1) + (b_1)(c_2)(a_3) + (b_2)(c_3)(a_1) + (c_1)(a_2)(b_3) + (c_2)(a_3)(b_1).$$

$$4) \quad I_2 = (a_1)(a_2)(b_3)(b_1)(c_1)(c_2) + (a_1)(a_2)(b_3)(b_2)(c_2)(c_1) + (a_1)(a_2)(b_1)(b_2)(c_1)(c_3) + (a_1)(a_2)(b_1)(b_3)(c_2)(c_3) + (a_1)(a_3)(b_1)(b_2)(c_1)(c_3) + (a_1)(a_3)(b_2)(b_3)(c_2)(c_3).$$

$$5) \quad D_2 = (a_1)(a_2)(b_1)(b_2)(c_1)(c_2) + (a_1)(a_2)(b_1)(b_3)(c_2)(c_3) + (a_1)(a_2)(b_2)(b_3)(c_1)(c_3) + (a_1)(a_3)(b_1)(b_2)(c_1)(c_3) + (a_1)(a_3)(b_2)(b_3)(c_2)(c_3) + (a_2)(a_3)(b_1)(b_2)(c_1)(c_3).$$

$$6) \quad I_3 = (a_1)(a_2)(a_3)(b_1)(b_2)(b_3)(c_1)(c_2)(c_3).$$

D_2 can be written as a minor

Convenient form to represent as
a determinant

$$D_2 = \begin{vmatrix} (a\alpha)(b\beta) & (b\beta)(c\gamma) & (a\gamma)(a\delta) \\ (b\alpha)(b\beta) & (b\beta)(b\gamma) & (b\gamma)(b\delta) \\ (c\alpha)(c\beta) & (c\beta)(c\gamma) & (c\gamma)(c\delta) \end{vmatrix},$$

and I_2 is the same determinant
expanded and all signs made pos-
itive.

Following Dr Hur's notation*
for indicating the collection degree
in Roman and Greek letters
respectively, the cases are re-
corded as follows:-

$$D_1(1, 0) ; \Delta_1(0, 3) ; D_2(6, 6) ;$$

$$I_1(3, 3) ; I_2(6, 6) ; I_3(1, 1) .$$

It is just as well to employ a
similar notation to indicate the
degree in the virtual coefficients
of the 3-point and 3-line respec-

* Ibid. p. 42.

being. We then have

$$D_1(1,0); \quad \Delta_1(0,1); \quad I_1(2,2);$$

$$I_1(1,1); \quad I_2(2,2); \quad I_3(3,3).$$

The only advantage of this form is that it gives the reason for the choice of subscripts attached to our six fundamental invariants.

From these 6 independent invariants we would expect to be able to form 4 independent absolute invariants, and such as found to be the case. Since an absolute invariant must be of degree zero in the three und. Roman letters, the 4 independent ones, (i.e. a set of 4) can be built up easily from the 6 above. Probably the simplest set is,

$$\frac{I_2}{D_2} \quad ; \quad \frac{I_1}{D_1 \Delta_1} \quad ; \quad \frac{I_1^2}{I_2} \quad ; \quad \frac{I_1 I_2}{I_3}.$$

That any other form of your de-

you can be kept up from there
 to give you a fairly good idea of what.

The example

$$\frac{I_1 \Delta_1 I_2}{I_2} = \frac{I_1}{I_2} \cdot \frac{I_1}{I_2} \cdot \frac{I_1}{I_2}$$

$$\frac{I_1^2}{I_2} = \frac{I_1^2}{I_2} \cdot \frac{I_1^2}{I_2}, \text{ and so on.}$$

The result was to be expected
 for the simple counting of contents
 here we find that two branches have
 at 4 abstract concepts.

It is observed that the D's are
 determinants hence change sign when
 two letters are interchanged. Of course
 when equated to zero this makes no
 difference. On the other hand this
 fact enables one at a glance to tell
 whether the D's enter to an odd or
 even power in any given expression
 form.

§ 2. Simplified Form of the Fundamental Elements.

If the 3-line be now taken
on the reference triangle, so that
coordinates of lines forming system
except Δ_1 , become homogeneous,
certain integral functions of the
Roman letters, i.e., of the coefficients
of the 3-point. Δ_1 , assume the value
unity. The simplification of the
form of the 3-symbols is given in
the following paragraph as a very
easy matter, for all coefficients of the
left α, β, γ and α', β', γ' are 1. In
absolutely construction of each letter
we need consider α, β, γ and α' .

* In Colla in an unpublished article
suggested a different complete system, based
almost exclusively on this fact.

shown at the end of the previous paper. By using these and the four fundamental determinants we reduce the very simple forms

$$D_1 = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

$$I_1 = a_1 b_2 c_3 + a_3 b_1 c_2 + a_2 b_3 c_1 \\ + a_1 b_3 c_2 + a_3 b_2 c_1 + a_2 b_1 c_3.$$

$$D_2 = \begin{vmatrix} a_2 a_3 & a_3 a_1 & a_1 a_2 \\ b_2 b_3 & b_3 b_1 & b_1 b_2 \\ c_2 c_3 & c_3 c_1 & c_1 c_2 \end{vmatrix}$$

$$I_2 = a_2 a_3 b_1 b_2 c_1 c_2 + a_1 a_2 b_2 b_3 c_3 c_1 + a_3 a_1 b_1 b_2 c_2 c_3 \\ + a_2 a_3 b_1 b_2 c_3 c_1 + a_1 a_2 b_3 b_1 c_2 c_3 + a_3 a_1 b_2 b_3 c_1 c_2.$$

$$I_3 = a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3$$

It has been shown that I_1 and I_2 are merely D_1 and D_2 expanded and all signs made plus is of great advantage in remembering these forms.

§3. Proof of the Completeness of the System.

It is obviously of primary importance to prove that the system as given is complete, i. that all invariant relations between the line triangles can be expressed in terms of the system proposed in the preceding paragraphs.

Take the 3-line as the reference triangle and call it T_1 . The 3-point, $(a\xi)(b\xi)(c\xi)=0$, we will call T_2 . If we took the 3-line generally, $(ax)(bx)(cx)=0$ we would define a natural invariant of the two triangles as a rational integral function of the coefficients, which has the invariant property and is unaltered by a permutation of the 3 lines or of

the 3 points, that is, by any permutation of a, b, c or of a, b, c .
is when the 3 line is taken as
the reference triangle, all rational
simultaneous invariants (except Δ ,
the discriminant of the 3 line which
tends to unity, but must be noted)
of T_1 and T_2 are homogeneous rational
integral functions of a, b, c , which
are unaltered by any permutation of
the letters or of the subscripts. The
converse is equally true and any
homogeneous, rational, integral func-
tion of the coefficients a, b, c , which
is unaltered by a permutation of
the letters or of the subscripts, has
the invariant property. Hence any
such invariant can be written down
in the most general form as the
sum of

$$I = \sum a_1^{l_1} a_2^{l_2} a_3^{l_3} b_1^{f_1} b_2^{f_2} b_3^{f_3} c_1^{k_1} c_2^{k_2} c_3^{k_3}$$

where the exponents are subject to the following conditions

$$l_1 + l_2 + l_3 = n$$

$$f_1 + f_2 + f_3 = n$$

$$l_1 + f_2 + f_3 = n$$

$$l_2 + f_1 + f_3 = n$$

$$l_1 + k_2 + k_3 = n$$

$$l_3 + f_3 + k_3 = n$$

The necessity of these conditions is evident.

We next prove the lemma:- Every individual term of I is a monomial where I is of the nth degree in the coefficients of the n-point, as the product of n factors of the type $a_1 b_1 c_1$ where $a_1 \neq b_1$.

To aid in establishing this lemma

$$a_1 b_1 c_1 = 1$$

$$a_1 b_1 c_1 = 1$$

$$a_2 b_1 c_1 = 1$$

$$a_2 b_1 c_1 = 1$$

$$a_3 b_1 c_1 = 1$$

$$a_3 b_1 c_1 = 1$$

consequently as long as a term contains any letter with any possible sub

script we can continue taking factors from it of type $a_k b_k c_k$, $k \neq k \neq k$.

But some exponents may become zero, ^{and others not}

and we must look at that case. We will suppose some exponent say $c_1 \neq 0$.

Then ~~from~~ our equations of condition become or tell us

$$c_1 > 0, \therefore c_2 < m, \quad c_3 < n \quad \text{for } \sum c_k = n$$

$$\text{also } f_2 + k_2 = 0, \quad f_3 + k_3 = 0$$

$$\text{and } f_1 < n, \quad k_1 < m$$

Hence $f_2 + f_3 > 0$ or f , would $= m$

and $k_2 + k_3 > 0$ or k , would $= m$

From these inequalities it follows

if $f_2 = 0$, $k_2 > 0$ & $f_3 > 0$ and since $c_1 > 0$

we have $a_1 b_3 c_2 = \beta_0$ as a factor.

If $k_3 = 0$, $f_3 > 0$, $k_2 > 0$, and again

~~we have~~ $a_1 b_3 c_2 = \beta_0$ as a factor.

both f_2 and $k_3 = 0$, Then $f_3 > 0$, $k_2 > 0$

and again $a_1 b_3 c_2 = \beta_0$ as a factor.

if $f_2 = 0$, or $k_2 = 0$, or both equal to 0

at the same time $\alpha_1, \beta_1, \alpha_2, \beta_2$ - 20
 will be a factor. Taking out the
 factor α_1 or β_1 , we have left a factor
 of some type is before of degree n ,
 instead of n . We can continue fac-
 toring out an α_i or a β_i , until the
 invariant form is expressed
 in terms of α_i and β_i . This proves
 our lemma and we can write

$$I = \sum \alpha_0^c \alpha_1^d \alpha_2^k \beta_0^e \beta_1^m \beta_2^n .$$

Now since I must remain unaltered
by all permutations of a, b, c and of
the subscripts 1, 2, 3, it must remain
 unaltered by all permutations of the
Greek letters and of their subscripts. To
 establish this; if we express the permu-
 tations as cycles in the case of the
 English letters it is an easy matter
 to prove the corresponding permutation
 of the Greek letters in cyclic form.

If (abc) represents a cyclic permutation we have

- (1). (abc) is equivalent to $(\alpha_0 \alpha_2 \alpha_1)(\beta_0 \beta_1 \beta_2)$
- (2). (123) " " " $(\alpha_0 \alpha_1 \alpha_2)(\beta_0 \beta_1 \beta_2)$
- (3). (bc) " " " $(\alpha_0 \beta_0)(\alpha_1 \beta_1)(\alpha_2 \beta_2)$
- (4). (23) " " " $(\alpha_0 \beta_0)(\alpha_1 \beta_2)(\alpha_2 \beta_1)$
- (5). (ab) " " " $(\alpha_0 \beta_1)(\alpha_1 \beta_2)(\alpha_2 \beta_0)$

this includes all independent types.

This discussion can be still further abbreviated by writing

$$\begin{aligned}\alpha_0 + \alpha_1 + \alpha_2 &= r_1, & \beta_0 + \beta_1 + \beta_2 &= s_1, \\ \alpha_0 \alpha_2 + \alpha_2 \alpha_0 + \alpha_0 \alpha_1 &= r_2, & \beta_1 \beta_2 + \beta_2 \beta_0 + \beta_0 \beta_1 &= s_2, \\ \alpha_0 \alpha_1 \alpha_2 &= \beta_0 \beta_1 \beta_2 = t_3\end{aligned}$$

$$(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_0)(\alpha_0 - \alpha_1) = r \quad (\beta_1 - \beta_2)(\beta_2 - \beta_0)(\beta_0 - \beta_1) = s.$$

Since any invariant I admits of the permutation $(\alpha_0 \alpha_1 \alpha_2)$ and contains a term $\alpha_0^l \alpha_1^m \alpha_2^k \beta_0^l \beta_1^m \beta_2^k$, it must contain the 3 terms obtained by cyclically advancing the α 's. Since it also admits the permutation $(\beta_0 \beta_1 \beta_2)$, it must

contain the terms obtained by repeatedly advancing the β 's. In short, we must retain the 9 terms

$$\sum_{(\beta_0, \beta_1, \beta_2)} \beta_0^l \beta_1^m \beta_2^n \sum_{(\alpha_0, \alpha_1, \alpha_2)} \alpha_0^l \alpha_1^m \alpha_2^n.$$

If $l=m=n$ or $l=m=n$, these 9 terms reduce to 3, and if both equalities exist simultaneously, they reduce to a single term. In any event we have the product of two alternating functions of $\alpha_0, \alpha_1, \alpha_2$ and $\beta_0, \beta_1, \beta_2$ respectively. Carrying out the same argument for the other terms of I , we find that

$$I = R(r, s, r_2, s_2, p_3, r, s)$$

where R is a rational, integral, isobaric function of its arguments. The subscripts indicate the weight, r and s being of weight 3.

As a next step, r and s may be assumed to occur to the first degree only, for r^2 and s^2 can both be

expressed rationally in terms of the other 5 quantities. In fact we have

$$(6) \quad \begin{aligned} r^2 &= r_1^2 r_2^2 - 4 r_1^3 p_3 + 18 r_1 r_2 p_3 - 4 r_2^3 - 27 p_3^2. \\ s^2 &= s_1^2 s_2^2 - 4 s_1^3 p_3 + 18 s_1 s_2 p_3 - 4 s_2^3 - 27 p_3^2. \end{aligned}$$

We also notice that the permutation $(\alpha_1 \alpha_2)(\beta_1 \beta_2)$ changes the sign of r and s . Hence r and s can occur only in the combination rs .

Therefore we can now write

$$I = R_1(r_1, s_1, r_2, s_2, p_3) + rs \cdot R_2(r_1, s_1, r_2, s_2, p_3)$$

Again, the permutation $(\alpha_0 \beta_0)(\alpha_1 \beta_1)(\alpha_2 \beta_2)$ interchanges r_1 and s_1 . Therefore I is unaltered by interchanging r_1 and s_1 . Or

$$(7) \quad R_1(r_1, s_1, r_2, s_2, p_3) = R_1(s_1, r_1, s_2, r_2, p_3).$$

Now take a term of R_1 as $r_1^c s_1^k r_2^e s_2^m p_3^n$, then from (7), R_1 must contain the sum of the 2 terms

$$p_3^n [r_1 s_1]^k [r_2 s_2]^m [r_1^a r_2^b + s_1^a s_2^b] = A_i, \text{ say,}$$

where for convenience we suppose $k \leq i$,
i.e. ℓ , $i - k = a$, $\ell - m = b$.

To reduce still further, let

$$p_3^n [r_1 s_1]^k [r_2 s_2]^m [r_1^a s_1^b + s_1^a r_2^b] = A_2$$

Then combining A_1 and A_2

$$\begin{aligned} A_1 + A_2 &= p_3^n [r_1 s_1]^k [r_2 s_2]^m (r_1^a + s_1^a)(r_2^b + s_2^b) \\ &= S_1 [r_1 + s_1, r_2 + s_2, r_1 s_1, r_2 s_2, p_3] \end{aligned}$$

$$\begin{aligned} A_1 - A_2 &= p_3^n [r_1 s_1]^k [r_2 s_2]^m (r_1^a - s_1^a)(r_2^b - s_2^b) \\ &= (r_1 - s_1)(r_2 - s_2) S_2 [r_1 + s_1, r_2 + s_2, r_1 s_1, r_2 s_2, p_3] . \end{aligned}$$

where S_i is a rational function of the arguments. This enables one to solve for A_i in terms of $(r_1 - s_1)(r_2 - s_2)$ and the 5 arguments of S_i . Carrying out the same process for all terms of R_1 we find

$$\begin{aligned} R_1 &= M_1 [r_1 + s_1, r_2 + s_2, r_1 s_1, r_2 s_2, p_3] \\ &\quad + (r_1 - s_1)(r_2 - s_2) M_2 [r_1 + s_1, r_2 + s_2, r_1 s_1, r_2 s_2, p_3] \end{aligned}$$

where M_i is a rational, integral, isobaric function of its arguments. R_2 can be expressed in the same way. Hence

Any rational, semi-ultra-invariant of T_1 and T_2 is a rational, integral, isobaric function of $r_1 + s_1, r_2 + s_2, r_1 s_1, r_2 s_2,$

p_3 , $(r_1 - s_1)(r_2 - s_2)$, and $r.s.$. Now These
 are themselves invariants
 seven arguments, hence we have as
 a final Theorem: -

The following seven invariants
 form a complete system of the
 simultaneous, rational invariants of T_1
 and T_2 :-

$$I_1 = r_1 + s_1,$$

$$J_2 = r.s.,$$

$$I_2 = r_2 + s_2,$$

$$J_3 = (r_1 - s_1)(r_2 - s_2);$$

$$I_3 = p_3,$$

$$I_6 = r.s.$$

$$I_4 = r_2 s_2,$$

Of these seven, the last two are
 skew. It does not follow from the
 argument presented that these seven
 are absolutely independent. In fact
 there is a syzygy connecting them,
 for, since we have already shown that
 r^2 and s^2 individually can be expressed
 in terms of the first six, it follows
 that I_6^2 can be expressed. Hence the

first six constitute a complete system.

This system of seven equations, which we have proven complete, was first suggested by Dr. Coble as one which might be available for the simple representation of all incidence relations between two triangles. A considerable amount of working with various possible combinations of these forms, which could be used as a fundamental or primary system, caused the writer to select the system presented in the body of this article as the simplest system available. This system is easily shown to be as good as the Coble system which has been proven complete.

As we have already shown

$$I_1 = r_1 + s_1, \quad D_1 = r_1 - s_1,$$

$$I_2 = r_2 + s_2, \quad D_2 = r_2 - s_2,$$

$I_3 = P_3$, as a primary system.

Clearly the Table System can be expressed in terms of these five. In the following form we may present:

$$I_1' = I_1 \quad I_2' = \frac{1}{4}(I_1' - I_1'')$$

$$I_2' = I_2 \quad I_3' = I_1, I_2$$

$$I_3' = I_3 \quad I_4' = \frac{1}{4}(I_2' - I_2'')$$

and of course I_6^2 can be expressed rationally although the form is somewhat long. Of course I_1 , which is unity when the 3-line is taken as the reference triangle (as in this paragraph) must be included in the complete system. Hence we have proven the fundamental theorem of this paragraph, viz. - The system of invariants proposed in the previous paragraph is complete, although for rational completeness we must add I_6 which has been defined above.

The principles employed in this paragraph to prove the completeness

of the system, (i.e. if any invariant contains a term $\alpha_0^l \alpha_1^7 \alpha_2^k \beta_0^l \beta_1^m \beta_2^n$, it will contain all terms obtained by permuting the α 's and β 's) will be found very useful in determining all invariants relations, or we need only consider one value about a single term of each type. This reduces the necessary algebra very materially. In some cases it is convenient to use the symbols α and β as defined in this section, but as they are unsymmetrical, this leads to complications.

It may be well to add the form of I_6 in terms of the coefficients of the three points:-

$$I_6 = (\alpha_2 \beta_3 \gamma_1 - \alpha_3 \beta_2 \gamma_1)(\alpha_2 \beta_1 \gamma_2 - \alpha_1 \beta_2 \gamma_2)(\alpha_2 \beta_1 \gamma_3 - \alpha_1 \beta_3 \gamma_3) \\ + (\alpha_2 \beta_1 \gamma_3 - \alpha_1 \beta_3 \gamma_3)(\alpha_1 \beta_2 \gamma_3 - \alpha_2 \beta_3 \gamma_3)(\alpha_1 \beta_2 \gamma_2 - \alpha_2 \beta_1 \gamma_2).$$

The meaning of $I_6 = 0$, will be shown later on page 51.

§ 4. Reciprocal or Dual Forms.

Coming to the importance of the dual forms so derived, we shall now consider the transformation of that invariant when the role of the two triangles is interchanged. That is when the one originally taken as the 3-line is taken as the 3-point and vice-versa. The formulas thus obtained will be found very useful, for if we know a certain projection relation exists between the 3-line and the 3-point due to the vanishing of a certain invariant form, then the vanishing of the reciprocal or dual form, which is found immediately by applying our formulas now to be found) will indicate the existence of the same relation between the

joins of the 3-point and the
 meets of the 3-lines. To get the
 dual forms in the general case
 would obviously be equivalent to re-
 placing each Greek and Roman
 letter in each of the fundamental
 invariants by their corresponding
 names in the determinants we have
 named Δ_1 and D_1 respectively. Having
 this in determining the dual forms
 we take the simplified form of
 the original system, for instance
 with the algebra as long. We take
 the dual form by formula.

$$D'_1 = \begin{vmatrix} b_2 c_3 - b_3 c_2 & a_3 c_2 - a_2 c_3 & a_1 a_2 - a_2 a_1 \\ b_3 c_1 - b_1 c_3 & a_1 c_3 - a_3 c_1 & a_2 a_3 - a_3 a_2 \\ b_1 c_2 - b_2 c_1 & a_2 c_1 - a_1 c_2 & a_3 a_1 - a_1 a_3 \end{vmatrix} \\
 = D_1$$

This is evidently a simple ap-
 plication of a well known theorem

in determinants; - If each term in
 a 3x3 determinant is replaced
 by its minor, The resultant is the
 transposed determinant squared.

$$\therefore D_1' = D_1^2.$$

D_1' is a 3x3 determinant the expansion of
 the determinant D_1' , with all six
 signs, becomes -

$$\begin{aligned} D_1' &= (b_2 c_3 - b_3 c_2)(a_1 c_3 - a_3 c_1)(a_1 b_2 - a_2 b_1) \\ &\quad + (b_3 c_1 - b_1 c_3)(a_2 c_1 - a_1 c_2)(a_3 b_1 - a_1 b_3) \\ &\quad + (b_1 c_2 - b_2 c_1)(a_3 c_2 - a_2 c_3)(a_3 b_1 - a_1 b_3) \\ &\quad + (b_2 c_3 - b_3 c_2)(a_2 c_1 - a_1 c_2)(a_3 b_1 - a_1 b_3) \\ &\quad + (b_3 c_1 - b_1 c_3)(a_3 c_2 - a_2 c_3)(a_1 b_2 - a_2 b_1) \\ &\quad + (b_1 c_2 - b_2 c_1)(a_1 c_3 - a_3 c_1)(a_2 b_3 - a_3 b_2), \\ &= \sum a_1^2 b_2^2 c_3^2 - \sum a_1^2 b_3^2 c_2^2 \\ &\quad - 4 \left[\sum a_1 a_2 b_2 b_3 c_3 c_1 - \sum a_1 a_2 b_3 b_1 c_2 c_3 \right]^*. \end{aligned}$$

and some of these terms $a_1 a_2 b_1 b_2 c_2$ go-
 ing out.

* In all places a figure over a summa-
 tion mark, indicates the number of terms in Σ .

This can be expressed rather easily in terms of our invariants, for it is of the second degree and by observation we see the D_i 's must enter to an odd, i.e. the first degree. Now

$$I, D_1 = \sum_{i=1}^3 a_i^2 b_i^2 c_i^2 - 2 \sum_{i=1}^3 a_i^2 b_i^2 c_i^2 + 2 \sum_{i=1}^3 a_i a_2 b_i b_3 c_i c_3 - 2 \sum_{i=1}^3 a_i a_2 b_i b_3 c_i c_3.$$

$$D_2 = \sum_{i=1}^3 a_i a_2 b_i b_3 c_i c_3 - \sum_{i=1}^3 a_i a_2 b_i b_3 c_i c_3$$

$$\therefore \underline{I_2'} = I, D_1 - 6 D_2.$$

I_2' and D_2' will be developed simultaneously from the determinant:-

$$I \begin{vmatrix} (b_3 c_1 - b_1 c_3) & (c_3 a_1 - c_1 a_3) & (a_3 b_1 - a_1 b_3) \\ (b_1 c_2 - b_2 c_1) & (c_1 a_2 - c_2 a_1) & (a_1 b_2 - a_2 b_1) \\ (b_2 c_3 - b_3 c_2) & (c_2 a_3 - c_3 a_2) & (a_2 b_3 - a_3 b_2) \end{vmatrix}$$

The expansion of this determinant is D_2' , and taken with all six signs positive it is I_2' . The problem now is to express these two forms in terms

of the invariants.

Before completing the determination of dual forms, it will be of advantage to write down a series of variations of terms of the same type of the 4th degree in the coefficients of the 2-forms, which designate them by arbitrary, chosen letters. As these variations are used frequently, this notation will be adhered to throughout the work.

Table of variations

$$\sum_1^3 a_1^2 b_2^2 c_3^2 - \sum_1^3 a_1^2 b_3^2 c_2^2 = A' - A''$$

$$\sum_1^2 a_1^2 b_2^2 b_3^2 c_3^2 - \sum_1^2 a_1^2 b_2^2 c_2^2 c_3^2 = B' - B''$$

$$\sum_1^9 a_1^2 a_2^2 b_1^2 b_2^2 c_3^2 - \sum_1^9 a_1^2 a_2^2 b_1^2 c_2^2 c_3^2 = C' - C''$$

$$\sum_1^{18} a_1^2 a_2^2 b_1^2 b_2^2 c_2^2 c_3^2 - \sum_1^{18} a_1^2 a_2^2 b_1^2 b_3^2 c_2^2 c_3^2 = D' - D''$$

$$\sum_1^3 a_1^2 a_2^2 b_2^2 b_3^2 c_3^2 - \sum_1^3 a_1^2 a_2^2 b_1^2 b_3^2 c_2^2 c_3^2 = E' - E''$$

$$\sum_1^3 a_1^2 a_2^2 a_3^2 b_1^2 b_2^2 c_2^2 c_3^2 - \sum_1^3 a_1^2 a_2^2 a_3^2 b_1^2 b_3^2 c_2^2 c_3^2 = F' - F''$$

$$\sum_1^6 a_1^2 a_2^2 b_1^2 b_3^2 c_3^2 c_1 - \sum_1^6 a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_1 = G' - G''$$

$$\sum_1^2 a_1^2 a_2^2 b_1^2 b_2^2 c_1 c_2 c_3^2 = H$$

$$\sum_1^1 a_1^2 a_2^2 b_1^2 b_2^2 c_1^2 c_2^2 c_3^2 = K$$

Of course the above pairs connected with the minus sign will often appear connected with the plus sign.

In that case we shall still further abbreviate the algebra by writing

$$\sum_1^6 a_1^4 a_2^4 a_3^4 = A' + A'' = A,$$

$$\sum_1^{18} a_1^4 b_2^3 b_3^3 c_2^3 c_3^3 = B' + B'' = B, \text{ etc., etc.}$$

It is well to remember that if one term of any of these summations appears, all must be present. So we need in every instance consider only a single term of each type to determine coefficients. With this notation the expansion of determinants (I), and consequently the expansion for D_2' and D_2'' presents no difficulty, except that of doing it right. It is unnecessary to give the expanded form of each term in the determinants, but merely the sum of

the three positive terms, which we will call Φ , and of the three negative terms which we will call Θ .

It follows that by direct substitution

$$\Phi = E' + 3E'' - 2D' + 2C' + C'' - 5F' + 6F'' - G'$$

$$\Theta = 3E' + E'' - 2D'' + C' + 2C'' + 6F' - 5F'' - G''$$

Hence adding and subtracting in turn

$$I_2' = 4E - 2D + 3C + F - G$$

$$D_2' = -2(E'E'') - 2(D'D'') + (C'C'') - 11(F'F'') - (G'G'')$$

Now as hinted at before, we can always tell if D_1 and D_2 (or both) enter to an odd or even degree. For if all terms of the same type are positive or all negative, then the D_i 's enter into every term of the invariant to an even degree. If however the terms of a given type are half positive and half negative then the D_i 's enter to an odd degree. This theorem requires no proof being evident, hence since

D_2' is of the 4th degree in the coefficients, and contains by above theorem the D_i 's to an odd degree it can contain only the terms $D_1^2 D_2$, $D_1^2 I_3$, $I_1 I_2 I_3$, $D_1^2 I_2$ and $I_1^2 I_2$.

Expressing these in terms of the summations just given we have

$$D_1^2 D_2 = 2(E'E'') + 2(D'D'') - (C'C'') + 11(F'F'') + (G'G'').$$

It is unnecessary to write down the terms at the 3rd, as we already know precisely the negative of D_2' .

$$\therefore \underline{D_2' = -D_1^2 D_2}.$$

Similarly I_2' can contain only the terms $D_1^2 I_2$, $I_1 D_1 D_2$, $D_1^2 I_3$ and $D_1^4 I_1$. But only the first was needed,

$$D_1^2 I_2 = C - 2D + 2E - F + G + 4H$$

$$I_1 D_1 D_2 = -C + 2E + 5F + G - 4H$$

$$D_1^2 I_3 = E + 2F - 2H$$

$$\therefore \underline{I_2' = D_1^2 I_2 - 2I_1 D_1 D_2 + 6D_1^2 I_3}, \text{ as we can}$$

check by a comparison with the sum of 2nd and 4th degree terms where D_1^4 are absent

the preceding page.

Some other 4th degree forms which were of frequent use in later computations will be placed here for reference.

$$I_1^2 I_2 = 2E + 2L + 13 + 11F + 9 - 4H$$

$$I_2^2 = -2F - 2H$$

$$I_1 I_2 = F$$

$$I_1^4 = A + 6E + 12C + 4G + 36F + 4B + 12D \\ + 24H + 6K$$

$$D_1^4 = A + 6E + 12C + 4G - 12F - 4B - 12D \\ + 24H + 6K$$

$$I_1^2 D_1^2 = A + 6E + 12C + 4G + 12F + 24H - 2K.$$

The derivation of these formulas is somewhat tedious as no more method is pointed out. They can be compared however by inspection with a corresponding number of actual results.

There remains the derivation of

the ideal of I_2 . We have

$$I_3' = (b_3c_3 - b_1c_1)(b_2c_1 - b_1c_2)(b_1c_2 - b_2c_1)(c_3a_1 - c_1a_2) \\ (c_3a_1 - c_1a_3)(c_1a_2 - c_2a_1)(a_2b_3 - a_3b_2)(a_3b_1 - a_1b_3)(a_1b_2 - a_2b_1).$$

By merely expanding this and so on, as in the previous case, the algebra becomes almost unmanageable. The following method, which involves the notation of the previous paragraph, serves to give much less laborious definition. The equations required are

$$\alpha_0\alpha_1\alpha_2 = 1, \quad \beta_0\beta_1\beta_2 = 1,$$

$$\alpha_0\alpha_1 = 1, \quad \beta_0\beta_1 = 1,$$

$$\alpha_0\alpha_1 = 1, \quad \beta_0\beta_1 = 1,$$

$$\alpha_0\alpha_1\alpha_2 = 1, \quad \beta_0\beta_1\beta_2 = 1,$$

$$\alpha_0\alpha_1 + \alpha_1\alpha_2 + \alpha_2\alpha_0 = \tau_2, \quad \beta_0\beta_1 + \beta_1\beta_2 + \beta_2\beta_0 = s_2,$$

$$\alpha_0\alpha_1\alpha_2 = \beta_0\beta_1\beta_2 = \tau_3 = s_3 = I_3,$$

and the previous method will

$$\alpha_0 = 1, \quad \tau_1, \quad \beta_0 = 1, \quad s_1,$$

$$\alpha_0 = 1, \quad I_2, \quad \beta_0 = 1, \quad I_2.$$

Next group the terms of I_3' thus—

$$1) [(b_1 c_3 - b_3 c_1)(c_3 a_1 - c_1 a_3)(a_1 b_1 - a_3 b_3)]$$

$$[(b_1 c_1 - b_3 c_3)(c_1 a_1 - c_3 a_3)(a_1 c_1 - a_3 c_3)]$$

$$[(b_1 c_2 - b_2 c_1)(c_2 a_3 - c_3 a_2)(a_3 b_1 - a_1 b_3)]$$

It is then very simple to express each of these three factors by means of the symbols just defined.

$$3) I_3' = (\alpha_0^2 - \alpha_0 S_1 + S_2 - \alpha_1 \alpha_2)(\alpha_1^2 - \alpha_1 S_1 + S_2 - \alpha_0 \alpha_2) \\ (\alpha_2^2 - \alpha_2 S_1 + S_2 - \alpha_0 \alpha_1).$$

Expanding the right hand side, collecting and simplifying as much as possible in same symbols,

$$4) I_3' = I_3(\alpha^3) - \sum^3 \alpha_i^3 \alpha_k^3 - I_3 r_2 S_1 - I_3 \bar{S}_1(\alpha^3) - \sum^6 \alpha_i^2 \alpha_k^3 S_i \\ + I_3 r_1 S_1^2 - \sum^3 \alpha_i^2 \alpha_k^2 S_i^2 - I_3 S_1^3 + \sum^3 \alpha_i^2 \alpha_k^2 S_{2i} + I_3 r_1 S_2 \\ - \sum^6 \alpha_i \alpha_k^3 S_{2i} + r_2 S_1^2 S_2 - r_1 S_{2i}^2 S_i + S_2^3 - r_2 S_2^2 + (\alpha^2) S_2^2.$$

$$\text{where } (\alpha^3) = \alpha_0^3 + \alpha_1^3 + \alpha_2^3, \text{ etc}$$

$$\text{and } i = 0, 1, 2; \quad k = 0, 1, 2, \quad i \neq k.$$

In order to get this expressed entirely in terms of r_i and S_i it was found best to employ the following

identities, which can be derived by simple calculations;

$$\sum_{i=1}^6 \alpha_i \alpha_K = r_1 r_2^2 - I_3 r_1 - 3 I_3 r_1^2.$$

$$\sum_{i=1}^6 \alpha_i \alpha_K^2 = r_1^2 r_2 - I_3 r_1 - 3 r_2^2.$$

$$\sum_{i=1}^6 \alpha_i^2 \alpha_K^2 = r_2^2 - 3 I_3 r_1.$$

$$(\alpha^3) = r_1^3 - 3 r_1 r_2 - 3 I_3.$$

$$(\alpha^2) = r_1^2 - 2 r_2.$$

$$\sum_{i=1}^6 \alpha_i^3 \alpha_K = r_2^3 - 3 I_3 r_1 r_2 - 3 I_3^2.$$

Substituting these values first in (4) we have

$$\begin{aligned} (5) \quad & I_3 r_1^3 - 3 I_3 r_1 r_2 + 3 I_3^2 - r_2^3 + 3 I_3 r_1 r_2 - 3 I_3^2 \\ & - I_3 r_2 s_1 - I_3 r_1^2 s_1 + I_3 r_2 s_1 + r_1 r_2^2 s_1 - I_3 r_2 s_1 \\ & - 2 I_3 r_1^2 s_1 + I_3 r_1 s_1^2 - r_2^2 s_1^2 + 2 I_3 r_1 s_1^2 - I_3 s_1^3 \\ & + r_2^2 s_2 - 2 I_3 r_1 s_2 + I_3 r_1 s_2 - r_1^2 r_2 s_2 + I_3 r_1 s_2 \\ & + 2 r_2^2 s_2 + r_2 s_1^2 s_2 - r_1 s_2^2 s_1 + s_2^3 - r_2 s_2^2 \\ & + r_1^2 s_2^2 - 2 r_2 s_2^2. \end{aligned}$$

Collecting these, and if

$$\begin{aligned} (6) \quad & I_3' = I_3 (r_1^3 - s_1^3) - (r_2^3 - s_2^3) - 3 I_3 (r_1^2 - r_1 s_1^2) \\ & + r_1 s_1 (r_2^2 - s_2^2) - (r_1^2 s_1^2 - r_2^2 s_2^2) + 3 r_1 r_2 (s_2 - s_1) - r_2 s_1 (s_1 - s_2). \end{aligned}$$

Before we can finally return to our system of accounts we need the following additional identities.

$$r_2 s_1 - r_1 s_2 = \frac{1}{2} (I_1 D_2 - I_2 D_1) .$$

$$r_1 r_2 - s_1 s_2 = \frac{1}{2} (I_1 I_2 + D_1 D_2) .$$

$$r_1 s_1 + r_2 s_2 = \frac{1}{2} (I_1 I_2 - I_1 D_2) .$$

$$r_2 s_2 = \frac{1}{4} (I_2^2 - D_2^2) .$$

$$r_1 s_1 = \frac{1}{4} (I_1^2 - D_1^2) .$$

Reducing (6) by steps we have

$$\begin{aligned} \bar{I}_3' &= D_1 I_3 (r_1^2 + r_1 s_1 + s_1^2) - D_2 (r_2^2 + r_2 s_2 + s_2^2) \\ &\quad - 3 D_1 I_3 r_1 s_1 + \frac{1}{4} I_2 D_2 (I_1^2 - D_1^2) \\ &\quad - \frac{1}{4} (I_1 D_2 - I_2 D_1) (I_1 I_2 - D_1 D_2) - 3 D_2 r_2 s_2 - \frac{1}{4} I_1 D_1 (I_2^2 - D_2^2) \\ &= D_1^3 I_3 - D_2^3 + \frac{1}{4} (I_1^3 I_2 D_1 - I_2 D_1^3 D_1 - I_1^2 I_2 D_2 \\ &\quad + I_1 I_2^2 D_1 + I_1 D_1 D_2^2 - I_2 D_1^2 D_2 - I_1 I_2^2 D_1 - I_1 D_1 D_2^2) \\ &= D_1^3 I_3 - D_2^3 + \frac{1}{4} (2 I_1 D_1 D_2^2 - 2 I_2 D_1^2 D_2) . \end{aligned}$$

Let us as a final form

$$(7) \quad \bar{I}_3' = D_1^3 I_3 - D_2^3 + \frac{1}{2} D_1 D_2 (I_1 D_2 - I_2 D_1) .$$

Summing up the results of this section we have the following Table of Dual Forms.

$$\begin{aligned}
 & I_1' = I_1 D_1 - 6 D_2 \\
 & D_1' = D_1^2 \\
 \text{A. } \left\{ \begin{aligned} I_2' &= D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2 \\ D_2' &= -D_1^2 D_2 \\ I_3' &= D_1^3 I_3 - D_2^3 + \frac{1}{2} D_1 D_2 (I_1 D_2 - I_2 D_1) . \end{aligned} \right.
 \end{aligned}$$

These forms are evidently not homogeneous, but may be made so by showing in each proper power of Δ_1 (which equals unity in the homogeneous form regularly taken) in each term. The dual table therefore for the 3-line and 3-point both taken generally is

$$\begin{aligned}
 & I_1' = I_1 D_1 \Delta_1 - 6 D_2 \quad , \quad D_1' \Delta_1' = D_1^2 \Delta_1^2 \\
 \text{B. } \left\{ \begin{aligned} I_2' &= I_2 D_1^2 \Delta_1^2 - 2 I_1 D_1 \Delta_1 D_2 + 6 D_2^2 \\ D_2' &= -D_1^2 \Delta_1^2 D_2 \\ I_3' &= I_3 D_1^3 \Delta_1^3 - D_2^3 - \frac{1}{2} D_1 \Delta_1 D_2 (I_1 D_2 - I_2 D_1 \Delta_1) \end{aligned} \right.
 \end{aligned}$$

Owing to the amount of algebra involved in calculating the dual forms, it is well to apply a very convenient check to the work. It is evident that if we interchange the role of the triangles a second time, they will be back to their original roles again. So again, only, if we carry out transformation (A) on the right hand sides of the equations (A) we ought to get back to our original system of invariants, (i.e. multiplied of course by some power of D). We will denote the result of this second substitution by the "double prime" or seconds symbol.

$$I_1'' = (I_1 D_1 - 6 D_2) D_1^2 + 6 D_1^3 D_2 = D_1^3 I_1$$

Comparing now the same transformation on the values we have,

$$D_1'' = D_1^4,$$

$$I_2'' = D_1^6 I_2,$$

$$D_2'' = D_1^6 D_2,$$

$$I_3'' = D_1^8 I_3.$$

While these formulas have no value of themselves they furnish a reasonable guarantee of the accuracy of the work up to the point.

§ 5. Some Invariant Relations of The 3-Point and The 3-Line.

Before working out any problems it should be noted, as pointed out before, that when the 3-line is seen as the reference triangle, Δ does not appear explicitly in the invariant forms, having assumed the value unity. It is necessary therefore, if the result is to be accurate for the general case, that the factor Δ , be incorporated in each term of the result to such a power as to make it of the proper degree in the Greek letters. If Δ , or D , is a factor of any resulting invariant form, it signifies at once that the condition under discussion exists when the

It is shown that Δ is itself independent of the degeneracy of the conic and is collinear respectively. In discussing most problems which arise in the study of the factor Δ , usually, Δ is not put, but we always assume that Δ is a square. Throughout a discussion, this usually assuming that the 3 lines are not concurrent, and Δ is therefore unity. A few of the simpler invariant relations will be calculated directly.

- 1) If the 3-points are collinear,

$$D_1 = 0.$$
- 2) If the 3 lines are concurrent,

$$D_2 = 0.$$

There are no general theorems, as the truth of these conditions can be seen at once.

3) If the 3-point is apolar to the 3-line,

$$I_1 = 0.$$

Let the 3-line be $x_1 x_2 x_3 = 0$, and the 3-point, $(a_1)(b_1)(c_1) = 0$. As is customary in polar calculations regard the x 's as operators, and operate with $x_1 x_2 x_3$ on $(a_1)(b_1)(c_1)$ in the usual way, and ask that the resulting function of the coefficients be equal to zero. Clearly the result of operating with $x_1 x_2 x_3$ on the expression $(a_1)(b_1)(c_1)$ in the equation of the 3-point. That is, the required condition is that

$$a_1 b_1 c_1 + a_2 b_2 c_1 + a_3 b_3 c_2 + a_1 b_3 c_2 + a_2 b_1 c_3 + a_3 b_2 c_1 = 0.$$

And thus, from our summary of the results of calculations, we conclude,

$$I_1 = 0.$$

4) If the 3 points and the 3 meets of the 3-line lie on a conic

$$\Delta_1^2 D_2 = 0.$$

For, taking as before the 3-line as the triangle of reference, the general conic on the 3 meets is

$$\alpha_1 x_2 x_3 + \alpha_2 x_3 x_1 + \alpha_3 x_1 x_2 = 0.$$

If now the 3-points $(a\xi) = 0$, $(b\xi) = 0$ and $(c\xi) = 0$ are to be on this conic

The following three equations must hold simultaneously:-

$$\alpha_1 a_2 a_3 + \alpha_2 a_1 a_3 + \alpha_3 a_1 a_2 = 0$$

$$\alpha_1 b_2 b_3 + \alpha_2 b_3 b_1 + \alpha_3 b_1 b_2 = 0$$

$$\alpha_1 c_2 c_3 + \alpha_2 c_3 c_1 + \alpha_3 c_1 c_2 = 0$$

Therefore eliminating $\alpha_1, \alpha_2, \alpha_3$ from the 3 equations, the required condition is

$$\begin{vmatrix} a_2 a_3 & a_3 a_1 & a_1 a_2 \\ b_2 b_3 & b_3 b_1 & b_1 b_2 \\ c_2 c_3 & c_3 c_1 & c_1 c_2 \end{vmatrix} = 0$$

But this is nothing more than
 $D_2 = 0$.

A study of the degree in the
 Greek letters in the general case
 show that Δ_1^2 must be divided
 as a factor, is therefore in general
 the condition is

$$\Delta_1^2 D_2 = 0,$$

is now started to prove.

- 6) If the 3 lines and the 3 joins
 of the 3-point are on a conic
 $D_1 D_2 = 0$.

For if the 6 lines are on a conic
 there must be a line η , such that
 the polyconic^{of η} as to the 3-point touches
 the 3 reference lines*. For this polyconic
 will touch the joins of the 3-point, for
 the Hessian on a triangle is the triangle

* Luvéque-G. and other Geometry 2.27 (5).

itself, and the polars of any line as to a circle of the third order, touches the curves in three points. Hence the characteristics of the Steiner system agree mutually, since each is touched once. It also follows directly from the fact of the circle known to them that the polar curve of any point as to a cubic passes through the double points, & the dual curve the polars of any line as to a cubic touches the double curve. Hence the polars of η as to the 3-point must return to a point η . But if I want find the polars of η as to the 3-point and see that the coefficients of ξ_i^2 be zero simultaneously.

Note the 3-point equation and its expansion, it can be written as follows.

$$(1) \sum_{c=1}^3 a_b c_c \xi_c^3 + \sum_{k=1}^3 (a_b c_k^2 + a_b c_c^2 + a_b^2 c_k) \xi_c^2 \xi_k + \sum_{l=1}^3 a_b c_c \xi_c \xi_l \xi_l$$

where $c \neq k \neq l$; $c = 1, 2, 3$; $k = 1, 2, 3$; $l = 1, 2, 3$.

Take the poleconic of η as to (1) and equate the coefficients of ξ_1^3 , ξ_2^3 and ξ_3^3 respectively to zero. Without writing down the complete equation of the poleconic these coefficients are respectively

$$3a_1 b_1 c_1 + (a_1 b_1 c_2 + a_1 b_2 c_1 + a_2 b_1 c_1) \eta_2 + (a_1 b_1 c_3 + a_1 b_3 c_1 + a_3 b_1 c_1) \eta_3 = 0$$

$$(a_2 b_1 c_1 + a_2 b_1 c_2 + a_2 b_2 c_1) \eta_1 + 3a_2 b_2 c_2 + (a_2 b_2 c_3 + a_2 b_3 c_2 + a_3 b_2 c_2) \eta_3 = 0$$

$$(a_3 b_1 c_1 + a_3 b_1 c_3 + a_3 b_3 c_1) \eta_1 + (a_3 b_2 c_2 + a_3 b_2 c_3 + a_3 b_3 c_2) \eta_2 + a_3 b_3 c_3 \eta_3 = 0$$

In order that these three equations hold simultaneously, the eliminant obtained by eliminating η_1, η_2, η_3 must vanish. That is

$$\begin{vmatrix} 3a_1 b_1 c_1 & a_1 b_1 c_2 + a_1 b_2 c_1 + a_2 b_1 c_1 & a_1 b_1 c_3 + a_1 b_3 c_1 + a_3 b_1 c_1 \\ a_2 b_1 c_1 + a_2 b_1 c_2 + a_2 b_2 c_1 & 3a_2 b_2 c_2 & a_2 b_2 c_3 + a_2 b_3 c_2 + a_3 b_2 c_2 \\ a_3 b_1 c_1 + a_3 b_1 c_3 + a_3 b_3 c_1 & a_3 b_2 c_2 + a_3 b_2 c_3 + a_3 b_3 c_2 & a_3 b_3 c_3 \end{vmatrix} = 0$$

The expansion of the determinant is somewhat long, but many terms cut out and the condition expressed by

This determinant vanishing reduces at once to

$$D_1 D_2 = 0.$$

Since this problem is exactly the dual of 6), the same result could have been obtained by merely taking the dual of D_2 from the formulae page 38. This example verifies the dualistic formulae and also the great advantage of having them.

7) The problem of Pask triangles in a normal collineation furnishes a nice example of calculating directly a well known invariant relation in terms of our fundamental system. The theorem to be proven is:

If the two triangles are such that the 3 points are a Pask triangle in a normal collineation having the 3 line for a fixed

Triangles

$$D_1(I, G - \frac{1}{2}I_2) = 0.$$

The proof is simple. The fixed triangle of the collineation is the triangle of reference, — the 3-lines.

Using a, b, c as the points to agree with my regularly adopted notation, the invariant collineation is written
 $d_1 \quad b \quad c.$

Then k_a is the transform of a to be on the side bc , k_b is to be on the side ac and k_c is on the side ab . This gives us at once 3 equations like

$$\begin{vmatrix} k_a a_1 & k_a a_2 & k_a a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = 0$$

If in the expansion of these determinants we use a_1, a_2, a_3 to denote respectively a, b, c



we can write the three equations

$$(2) \begin{cases} k_1 a_1 \alpha_1 + k_2 a_2 \alpha_2 + k_3 a_3 \alpha_3 = 0, \\ k_1 b_1 \beta_1 + k_2 b_2 \beta_2 + k_3 b_3 \beta_3 = 0, \\ k_1 c_1 \gamma_1 + k_2 c_2 \gamma_2 + k_3 c_3 \gamma_3 = 0. \end{cases}$$

Now these three equations must hold for all values of k , hence eliminating the k 's we have as the necessary and sufficient condition that

$$(3) \begin{vmatrix} a_1 \alpha_1 & a_2 \alpha_2 & a_3 \alpha_3 \\ b_1 \beta_1 & b_2 \beta_2 & b_3 \beta_3 \\ c_1 \gamma_1 & c_2 \gamma_2 & c_3 \gamma_3 \end{vmatrix} = 0$$

Expanding this determinant, replacing the Greek letters by their equivalents in Roman letters, and collecting terms, the result can be written

$$(4) \frac{6}{5} a_1^3 a_2^3 a_3^3 - \frac{18}{5} a_1^3 a_2^2 a_3^2 + \frac{18}{5} a_1^2 a_2^3 a_3^2 - 6 a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3 = 0$$

In this the D_i 's must enter to an even degree, and it turns out that

I, D_1^2 and $D_1 D_2$ are the only combinations that enter. So (4) reduces at once to $I, D_1^2 - 3 D_1 D_2$, or as before the condition is

$$D_1(I, D_1 - 3 D_2) = 0.$$

8) As a final example of this section we will look for the meaning of $I_6 = 0$, or what is the same thing, prove the theorem -

If the two triangles are in perspective then

$$I_6 = 0$$

As we saw I_6 is composed of six binomials as two linear in the coefficients, each factor corresponding to a particular ordering of the perspective. For example, by way of proof, suppose we ask that the lines joining $a, a'; b, b'; c, c'$ and $a, b, c; a', b', c'$ respectively

must pass through the intersection of the three given lines are

$$a_1 x_2 - a_2 x_1 = 0,$$

$$b_1 x_2 - b_2 x_1 = 0,$$

$$c_1 x_2 - c_2 x_1 = 0,$$

and consequently the condition that they must meet in a point is

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = 0.$$

$$\text{or } (a_3 b_2 - a_2 b_3) = 0.$$

And in the same way each ordering requires one factor of I_6 to vanish.

The theorem can also be stated:

If the two triangles are such that there exists a conic, such that the 3 lines are the polars of the 3 points as to that conic,

$$I_6 = 0.$$

All the simpler relations discussed

by Dr. Sherr could be taken up
 cases independently and the condi-
 tions expressed in terms of our pre-
 sent system. But since the present
 system has been found complete Dr.
 Sherr's conclusions must be directly in-
 ferrible in terms of the present one.
 By constructing such a transformation
 table it becomes possible to take ad-
 vantage of it with less by the
 former writer. In addition the
 comparison there afforded is not with-
 out interest, so a paragraph will
 be devoted to the formation of the
 arguments of Sherr's conclusions in
 terms of the present one.

56. Expression of Three Quadratic Invariants in Terms of the Second System.

From three fundamental invariants as derived from the characteristic equation we have invariants

$$I_1 = \sum E_{ii}$$

$$I_2 = \sum (B_{ii} E_{ii} + B_{jj} E_{jj})$$

$$I_3 = \begin{vmatrix} B_{11} & B_{12} & B_{13} \\ B_{21} & B_{22} & B_{23} \\ B_{31} & B_{32} & B_{33} \end{vmatrix}$$

The B 's are in turn defined in the general case as follows

$$B_{11} = \alpha_1 (\beta \gamma)_1 + \beta_1 (\gamma \alpha)_1 + \gamma_1 (\alpha \beta)_1$$

$$B_{22} = \alpha_2 (\beta \gamma)_2 + \beta_2 (\gamma \alpha)_2 + \gamma_2 (\alpha \beta)_2$$

$$B_{33} = \alpha_3 (\beta \gamma)_3 + \beta_3 (\gamma \alpha)_3 + \gamma_3 (\alpha \beta)_3$$

$$B_{21} = \alpha_2 (\beta \gamma)_1 + \beta_2 (\gamma \alpha)_1 + \gamma_2 (\alpha \beta)_1$$

and so on for $B_{33}, B_{31}, B_{13}, B_{23}$ & B_{32} .

The system $(\gamma)_1, \dots, (\gamma)_3$, etc., may be taken as special symbols, and

$$(3)_{\ell} = a_{\ell}(1^2/2r) + b_{\ell}(2^2/3r) + c_{\ell}(3^2/4r),$$

But finally

$$(1-2/r) = (1-3)(2/3) + (1-2)(2/3),$$

(1-2) etc., are multiples and quotients.

Thus we have captured a process to enable the reader to write out any term in full and verify the result which follows. These formulae simplify very materially if we now take the series as reference (multiples), for values

$$\alpha_L \beta_K \gamma_L = 0, \alpha_L \beta_K \gamma_K = 0 = \alpha_L \beta_K \gamma_L = \alpha_K \beta_L \gamma_L.$$

$$\sum \alpha_L \beta_K \gamma_L = 1; \quad L=1,2,3, \quad K=1,2,3, \quad L=1,2,3, \quad \text{etc.}$$

So we need only retain terms containing α, β, γ (owing to symmetry) and replace it everywhere by unity. The new case the result is follows,

$$B_{11} - B_{22} - B_{33} = \sum a_{\ell} b_{\ell} c_{\ell},$$

$$B_{11} = \sum a_{\ell} b_{\ell} c_{\ell} + (1, 1, 1, 1, 1, 1),$$

$$B_{11} = 2(a_{11} + a_{22} + a_{33} + a_{44} + a_{55} + a_{66}),$$

is also invariant.

$$B_{ij} = 2(a_j b_i c_k + a_j b_k c_j + a_k b_j c_i).$$

Or we can write down, where the four invariants are those on the left and will be marked with a bar merely to avoid confusion.

$$\bar{I}_1 = \sum_{i=1}^3 B_{ii} = 3 \sum_{i=1}^3 a_i b_i c_i = 3I_1.$$

$$\bar{I}_2 = \sum_{i=1}^3 (B_{21} B_{33} - B_{23} B_{31})$$

$$= 3 \left[\sum_{i=1}^3 a_i b_i c_i \right]^2 - 4 \left[(a_3 b_3 c_1 + a_3 b_1 c_3 + a_1 b_3 c_3) \right.$$

$$+ (a_2 b_2 c_1 + a_2 b_1 c_2 + a_1 b_2 c_2) + (a_3 b_3 c_2 + a_3 b_2 c_3 + a_2 b_3 c_3) (a_1 b_1 c_2 + a_1 b_2 c_1 + a_2 b_1 c_1) \left. \right]$$

$$+ (a_2 b_2 c_3 + a_2 b_3 c_2 + a_3 b_2 c_2) (a_1 b_1 c_3 + a_1 b_3 c_1 + a_3 b_1 c_1) \left. \right]$$

$$= 3I_1^2 - 4 \left(\sum_{i=1}^3 a_i^2 b_i b_i c_i c_i + 3 \sum_{i=1}^3 a_i a_3 b_i b_i c_i c_i \right)$$

$$= 3I_1^2 - (I_1^2 - D_1^2 - 12I_2) = 2I_1^2 + D_1^2 - 12I_2,$$

as is easily verified.

$-\bar{I}_3 = -\Delta D \bar{V}$ is more difficult to

transform and separate. We can

use the following identity

$$-\bar{I}_3 = \begin{vmatrix} I_1 & 2(a_2b_1c_1 + a_2b_2c_2 + a_2b_3c_3) & 2(a_3b_1c_1 + a_3b_2c_2 + a_3b_3c_3) \\ 2(a_1b_1c_3 + a_1b_2c_2 + a_1b_3c_1) & I_1 & 2(a_3b_3c_1 + a_3b_1c_3 + a_3b_2c_2) \\ 2(a_1b_1c_2 + a_1b_2c_1 + a_1b_3c_3) & 2(a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3) & I_1 \end{vmatrix}$$

Expanding this determinant

$$\begin{aligned} &= I_1^3 + 8(a_1b_1c_3 + a_1b_2c_2 + a_1b_3c_1)(a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3) \\ &\quad + 8(a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3)(a_3b_3c_1 + a_3b_1c_3 + a_3b_2c_2) \\ &\quad + 8(a_1b_1c_2 + a_1b_2c_1 + a_1b_3c_3)(a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3)(a_3b_3c_1 + a_3b_1c_3 + a_3b_2c_2) \\ &\quad - 11I_1[(a_1b_1c_3 + a_1b_2c_2 + a_1b_3c_1)(a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3) \\ &\quad + (a_2b_2c_1 + a_2b_1c_2 + a_2b_3c_3)(a_3b_3c_1 + a_3b_1c_3 + a_3b_2c_2) \\ &\quad + (a_3b_3c_1 + a_3b_1c_3 + a_3b_2c_2)(a_1b_1c_2 + a_1b_2c_1 + a_1b_3c_3)] \end{aligned}$$

= Since the last expression was found in the previous paragraph, page to be equal to $\frac{1}{4}(I_1^2 - D_1^2 + 12I_2)$

$$\begin{aligned} &= I_1^3 + 16 \sum_{18} a_1 a_2 a_3 b_1^2 b_2^2 c_1^2 c_2^2 + 8 \sum_{12} a_1^2 a_2^2 b_1^2 b_2^2 c_1^2 c_2^2 \\ &\quad + 48 a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3 - I_1(I_1^2 - D_1^2 + 12I_2) \end{aligned}$$

whence by direct calculation we get

$$\begin{aligned} &= I_1^3 + 12I_1 I_2 - 4I_1 I_2 - I_1^3 + I_1 I_1^2 - 12I_1 I_2 \\ &= I_1 D_1^2 - 4D_1 D_2 = D_1(I_1 D_1 - 4D_2) \end{aligned}$$

And since \bar{D} and \bar{D} are clearly the same as L , in D_1 , N is found

at once. For $\bar{I} = 1, D = I_1$ and

$$-\bar{A} \bar{I} \bar{N} = L_1 (I_1, I_1 - 1)$$

$$N = I_1 D - I_1 D_1$$

In this instance as in general we must always see that Δ_1 is inserted to a proper power in each term when the 3-line is taken generally.

Summarizing these various results in the form of a table, which we can use in translating all of the above results immediately in terms of the present table, we have the left hand two lines as follows:

$$D = D_1$$

$$\Delta = \Delta_1$$

$$\bar{I}_1 = -\bar{I}_1$$

$$\bar{I}_2 = -\bar{I}_1^2 - I_1^2 + 2 I_1$$

$$\bar{N} = -\bar{I}_1 D_1 + I_1 D_1$$

By the aid of the table we will

write down the equivalents of the results tabulated by Dr. Hesse on pages 50 and 51 of his article.

The 3-point de-
generates, if

$$D_1 = 0.$$

The 3 point is
apolar to the
3-line, if

$$I_1 = 0.$$

The meets of the
3-lines are apolar
to the joins of the
3 point, if

$$I_1 D_1 D_2 - 6 D_3 = 0.$$

The 3-line de-
generates, if

$$D_1 = 0.$$

The 3-line is
apolar to the
3 point, if

$$I_1 = 0.$$

The joins of the
3-point are apolar
to the meets of the
3-line, if

$$I_1 D_1 D_2 - 6 D_3 = 0.$$

A conic circumscribed to the 3-point and apolar to the 3-line exists if

$$I, D, \Delta, -2D_2 = 0.$$

A point conic apolar to both the 3-point and the 3-line exists if

$$D_1^2 D_2 = 0.$$

A conic circumscribed about both the 3-point and the 3-line exists if

$$\Delta_1^2 D_2 = 0.$$

There exists a point whose

A conic inscribed in the 3-line and apolar to the 3-point exists if

$$I, D, \Delta, -2D_2 = 0.$$

A line conic apolar to both the 3-line and the 3-point exists if

$$\Delta_1^2 D_2 = 0.$$

A conic inscribed to both the 3-point and the 3-line exists if

$$D_1^2 D_2 = 0.$$

There exists a line whose

conic as to the 3-line is apolar to the 3-point if
 $D, \Delta, (I, D, \Delta, -4D_2) = 0$.

The three polar lines as to the 3-line, of the points of the 3-point taken two at a time, meet in a point if

$$\Delta, (I, D, \Delta, -4D_2) = 0.$$

There exists a collineation carrying the 3-point and a fixed triangle, which sends each line of the 3-line into a point on the ob-

polar as to the 3-point is apolar to the 3-line if
 $D, \Delta, (I, D, \Delta, -4D_2) = 0$.

The three polar points as to the 3-point, of the lines of the 3-line taken two at a time, lie on a line if

$$D, (I, D, \Delta, -4D_2) = 0.$$

There exists a collineation carrying the 3-line and a fixed triangle, which sends each line of the 3-point into a line through the

point) and if
 $A_1(I, D, A_1 - 3D_2) = 0$.

There exists a
 conic passing
 through the meets of the 3-
 line as fixed points
 which sends each
 point of the 3-point
 into a point on the
 join of the other
 two if

$$I, D, A_1 - 3D_2 = 0.$$

There exists a
 point, such that its
 polar conic as to the
 joins of the 3-point
 is apolar to the
 meets of the 3-line

opposite, and if
 $D_1(I, D, A_1 - 3D_2) = 0$.

There exists a
 conic passing
 through the joins of the 3-
 point as fixed lines
 which sends each
 line of the 3-line
 into a line through
 the meet of the
 other two if

$$I, D, A_1 - 3D_2 = 0.$$

There exists a
 line such that its
 conic polar as to
 the meets of the 3-line
 is apolar to the
 joins of the 3-point

if

$$D_1^2 \Delta_1^2 (I, D, \Delta_1 - 2 D_2) = 0.$$

if

$$D_1^2 \Delta_1^2 (I, D, \Delta_1 - 2 D_2) = 0.$$

Another Theorem adapted from Hume's article is:-

The exists a line conic touching the circle of the 3-point and equal to the 3-line if

$$D_1^2 (I, D, \Delta_1 - 4 D_2) = 0.$$

As is seen from this summary, all Hume's & variant forms are members of the pencil

$$I, D, \Delta_1 + \lambda D_2 = 0.$$

As will be more evident from subsequent discussion, if two of the points are taken at the circular points at infinity, and the third point is taken variable, this pencil becomes the pencil of circles of which the Feuerbach circle and the circumcircle are members. It will

be observed that 'parallel' theorems in the two columns are not dual in the sense we used that term in deriving the dual forms of the fundamental invariants.

We might add here a pair of dual theorems:-

If one of the 3-
points lies on either
of the 3 lines

$$I_3 = 0.$$

If a nest of the
3-line lies on a point
of the 3-point

$$2D_1' D_2' D_3' + 2D_2' D_1' D_3' + 2D_3' D_1' D_2' = 0.$$

The theorem on the left is almost obvious. For if $(a\xi) = 0$ say is to be on $x_1 = 0$, $x_2 = 0$ or $x_3 = 0$, $a_1 = 0$, $a_2 = 0$ or $a_3 = 0$ respectively. In either case I_3 vanishes for $(b\xi) + (c\xi)$. The Theorem on the right is gotten by using the dual transformation formulae. The powers of L_i have not been inserted.

It may be worthy of note that

we have found a simple meaning for the vanishing of each of the fundamental invariants, including I_2 , with the exception of I_1 . Several indirect interpretations are available, but probably the best geometrically is the one on page 134.

§ 7. Condition That a Conic may
be Inscribed in one Triangle and
Circumscribed about the Other.

To find the invariant condition on two triangles such that a conic may be drawn touching the three sides of one triangle and on the vertices of the other is of particular interest and will be discussed at length. An attempt to solve this problem was in fact the genesis of this article. It is in general of no special import whether we regard the triangle taken as the reference triangle as a 3-line or a 3-point. But as a matter of consistency we shall speak of having taken the 3-line as triangle.

of reference, and shall speak
of the line as a
3-line.

We shall first take the polar
conics of a, b and c as seen as
to the 3-line, - The reference triangle.

They are

$$(1). a_1 x_2 x_3 + a_2 x_3 x_1 + a_3 x_1 x_2 = 0.$$

$$(2). b_1 x_2 x_3 + b_2 x_3 x_1 + b_3 x_1 x_2 = 0.$$

$$(3). c_1 x_2 x_3 + c_2 x_3 x_1 + c_3 x_1 x_2 = 0.$$

Now take any line η of (1), the
polar conic of a as to the refer-
ence 3-line, and the poloconic of
 η will pass through a .* (Cramer calls
the poloconic the conic polar.) Hence
it follows that if the three polar
conics (1), (2) and (3), find a common

* Salmon - Lessons in Modern Geom.
p 202. Clebsch, "Lecons sur la Geometrie, Vol II
part. II. See also Darboux, page 276, ff.

line, the poloconic of these lines
as to the 3-line would be one
all three points x, y, z , and c . But
further, this poloconic would also
touch the three reference lines, x, y, z .
For the poloconic of any line is to
a curve of the third order touching
the Hessian of the curve in three
points.* But the Hessian, in case
the curve is a triangle, is the
triangle itself, and since all three
sides of the triangle enter sym-
metrically, the poloconic would
touch each line of the Hessian
once. That this poloconic touches the
three lines can also be shown directly
as the dual of the well known the-
orem that the polar conic of any
point is to a cubic curve in an all
* "Reine Geometrie" *Erster Band* (Halle 1868) p. 116.

the double points of the cubic. Polar
conic and polar cone are dual terms

Consequently our problem is
now reduced to finding the con-
dition that the above three polar
cones may have a common line.
Salmon* gives the condition that
three point cones have a common
point as $T^2 = 64M$, where T and
 M are invariants of the net of con-
ics determined by the three base
conics. This meaning need not be
repeated here. So for three line
cones to have a common line
we need only form the line equa-
tions of (1), (2), (3) and form the in-
variants for them, corresponding to T
and M and express the results in
our present system.

*

Conic Sections pp 365-6.

The line equations of the three polar conics (1), (2), (3), can be written down in the usual way as

$$(4). \quad a_1^2 \xi_1^2 + a_2^2 \xi_2^2 + a_3^2 \xi_3^2 - 2a_2 a_3 \xi_2 \xi_3 - 2a_3 a_1 \xi_3 \xi_1 - 2a_1 a_2 \xi_1 \xi_2 = 0 = U.$$

$$(5). \quad b_1^2 \xi_1^2 + b_2^2 \xi_2^2 + b_3^2 \xi_3^2 - 2b_2 b_3 \xi_2 \xi_3 - 2b_3 b_1 \xi_3 \xi_1 - 2b_1 b_2 \xi_1 \xi_2 = 0 = V.$$

$$(6). \quad c_1^2 \xi_1^2 + c_2^2 \xi_2^2 + c_3^2 \xi_3^2 - 2c_2 c_3 \xi_2 \xi_3 - 2c_3 c_1 \xi_3 \xi_1 - 2c_1 c_2 \xi_1 \xi_2 = 0 = W.$$

Now any set of points $M=0$, requires that one of the web be a double line, so in a web of line conics as determined by U , V and W , $M=0$ requires that one of the web $lU + mV + nW$ be a double point. In that case the reciprocal of that particular one of the web must vanish identically.

For a more detailed treatment see Salmon's *Conic Sections* - p. 566.

for point conics, the reciprocals
or dual of

$$(7) \quad lU + mV + nW = 0$$

can be written in abridged form

$$(8) \quad l^2\Sigma + m^2\Sigma' + n^2\Sigma'' + mn\phi_{23} + nl\phi_{31} + lm\phi_{12} = 0$$

where the Σ 's are the reciprocals
of U , V and W respectively and
the ϕ 's are the Clebschians or
intermediates of the same taken
two at a time. By the term Clebsch-
ian or intermediate is meant the
form arising in this way. If, in
symbolic notation, $(a\xi)^2 \equiv (b\xi)^2 = 0$ is
a point conic then $|abx|^2 = 0$ is the
point equation, ^{**} where the symbol
 $|abx|$ means the 3-row determinant
but if $(a\xi)^2$ and $(b\xi)^2$ are distinct
conics, then $|abx|^2$ is a covariant
(really contravariant) point conic
Clebsch "Lecons" Vol I p. 348, gives this in detail.

which we will call the Clebschian.*
In Salmon's non-symbolic notation** the Clebschian of two such conics given in his well known general form is

$$\begin{aligned}\phi = & (bc' + b'c - 2ff')\xi^2 + (ca' + c'a - 2gg')\eta^2 \\ & + 2(b'a' - a'b - 2k')\xi + 2(gh' + g'h - af' - a'f)\xi\eta \\ & + 2(hf' + h'f - g'g - g'g')\eta + 2(fg' - f'g - k'h - k'h')\xi\eta.\end{aligned}$$

This form can easily be identified with the much simpler looking symbolic form. Either might be used in continuing our work (but in the present case since U , V & W are precisely $(a\xi)^2$, $(b\xi)^2$ and $(c\xi)^2$, save as to the sign of the product terms, it is obviously of advantage to use the symbolic

* Hux. uses the term intermediate, p. 44.

** See also Cox., Trans. Am. Soc. Vol IV, p. 10.

*.

Conic Sections, p. 344.

formula for the Clebschans can be written down at once by expanding $|ax|^2$, $|bcx|^2$ and $|cax|^2$, if we make the proper changes of sign after expansion.

For Σ we would naturally expect (since Σ' was the reciprocal of (1)) that we would get

$$2, x_2 x_3 + a_2 x_3 x_1 + a_3 x_1 x_2 = 0 \text{ again,}$$

but the ever-present outside factor may not be omitted in this case for reasons which are evident. So we have finally the values for the quantities in (8) the following:

$$(9). \Sigma = 4 a_1 a_2 a_3 (a_1 x_2 x_3 + a_2 x_3 x_1 + a_3 x_1 x_2).$$

$$(10). \Sigma' = 4 b_1 b_2 b_3 (b_1 x_2 x_3 + b_2 x_3 x_1 + b_3 x_1 x_2).$$

$$(11). \Sigma'' = 4 c_1 c_2 c_3 (c_1 x_2 x_3 + c_2 x_3 x_1 + c_3 x_1 x_2).$$

$$\begin{aligned}
 (12) \cdot \phi_{12} &= (a_2 b_3 - a_3 b_2)^2 x_1^2 + (a_1 b_3 - a_3 b_1)^2 x_2^2 + (a_1 b_2 - a_2 b_1)^2 x_3^2 \\
 &+ (a_3 b_1 - a_1 b_3)(a_1 b_2 - a_2 b_1) x_2 x_3 \\
 &+ (a_1 b_2 - a_2 b_1)(a_2 b_3 - a_3 b_2) x_3 x_1 \\
 &+ (a_2 b_3 - a_3 b_2)(a_3 b_1 - a_1 b_3) x_1 x_2 = 0
 \end{aligned}$$

$$\begin{aligned}
 (13) \cdot \phi_{23} &= (b_2 c_3 - b_3 c_2)^2 x_1^2 + (b_3 c_1 - b_1 c_3)^2 x_2^2 + (b_1 c_2 - b_2 c_1)^2 x_3^2 \\
 &+ (b_3 c_1 - b_1 c_3)(b_1 c_2 - b_2 c_1) x_2 x_3 \\
 &+ (b_1 c_2 - b_2 c_1)(b_2 c_3 - b_3 c_2) x_3 x_1 \\
 &+ (b_2 c_3 - b_3 c_2)(b_3 c_1 - b_1 c_3) x_1 x_2 = 0
 \end{aligned}$$

$$\begin{aligned}
 (14) \cdot \phi_{31} &= (c_2 a_3 - c_3 a_2)^2 x_1^2 + (c_3 a_1 - c_1 a_3)^2 x_2^2 + (c_1 a_2 - c_2 a_1)^2 x_3^2 \\
 &+ (c_3 a_1 - c_1 a_3)(c_1 a_2 - c_2 a_1) x_2 x_3 \\
 &+ (c_1 a_2 - c_2 a_1)(c_2 a_3 - c_3 a_2) x_3 x_1 \\
 &+ (c_2 a_3 - c_3 a_2)(c_3 a_1 - c_1 a_3) x_1 x_2 = 0.
 \end{aligned}$$

Following Salmon's determinant
in for M ,*

$$(15) \quad M = \begin{vmatrix} A & B & C & F & G & H \\ A' & B' & C' & F' & G' & H' \\ A'' & B'' & C'' & F'' & G'' & H'' \\ A_{23} & B_{23} & C_{23} & F_{23} & G_{23} & H_{23} \\ A_{31} & B_{31} & C_{31} & F_{31} & G_{31} & H_{31} \\ A_{12} & B_{12} & C_{12} & F_{12} & G_{12} & H_{12} \end{vmatrix}$$

*

Conic sections p. 366

where A, B, C, F, G, H are the coefficients of $x_1^2, x_2^2, x_3^2, x_1x_2, x_2x_3, x_3x_1$ respectively in Σ' . Let for the other three rows, we have the coefficients of $\Sigma', \Sigma'', \Phi_{23}, \Phi_{31}$ and Φ_{12} .

Substituting in (13) the actual coefficients found in equations (1)-(14) we have

(1) $M_1 =$

0	0	0	$2a_1^2a_2a_3^2, 2a_1a_2^2a_3, 2a_1a_2a_3^2$
0	0	0	$2b_1^2b_2b_3, 2b_1b_2^2b_3, 2b_1b_2b_3^2$
0	0	0	$2c_1^2c_2c_3, 2c_1c_2^2c_3, 2c_1c_2c_3^2$
$(a_3b_3-a_3b_3)^2, (a_3b_1-a_1b_3)^2, (a_1b_2-a_2b_1)^2,$	~	~	~
$(b_2^2c_3-b_2c_3)^2, (b_3c_1-b_1c_3)^2, (b_1c_2-b_2c_1)^2,$	~	~	~
$(c_1a_3-c_3a_1)^2, (c_3a_2-c_2a_3)^2, (c_2a_1-c_1a_2)^2,$			

It is not necessary to write down explicitly the wave strokes, as their complementary factors are zeros. So M at once reduces to the product of two

Three more determinants are

$$(11) \quad M =$$

$$\begin{vmatrix} (a_2 b_3 - a_3 b_2)^2 & (a_3 b_1 - a_1 b_3)^2 & (a_1 b_2 - a_2 b_1)^2 \\ (b_2 c_3 - b_3 c_2)^2 & (b_3 c_1 - b_1 c_3)^2 & (b_1 c_2 - b_2 c_1)^2 \\ (c_2 a_3 - c_3 a_2)^2 & (c_3 a_1 - c_1 a_3)^2 & (c_1 a_2 - c_2 a_1)^2 \end{vmatrix} \\ \times \begin{vmatrix} 2a_1^2 a_2 a_3 & 2a_1 a_2^2 a_3 & 2a_1 a_2 a_3^2 \\ 2b_1^2 b_2 b_3 & 2b_1 b_2^2 b_3 & 2b_1 b_2 b_3^2 \\ 2c_1^2 c_2 c_3 & 2c_1 c_2^2 c_3 & 2c_1 c_2 c_3^2 \end{vmatrix}$$

Each of these determinants is readily expressed in terms of nine invariants. The latter one is equal to

$$(12) \quad \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} \\ = 8 I_3 D,$$

The first determinant is itself not so simple, but is recognized as the trace of

$$\begin{vmatrix} a_1^3 & a_2^3 & a_3^3 \\ a_1^2 & a_2^2 & a_3^2 \\ a_1 & a_2 & a_3 \end{vmatrix}$$

which is only of the second degree and is equal to

$$(19). \quad I_1 D_1 - 2 D_2.$$

Applying the Weierstrass transformation formulae to this, we get the expression of the first term or factor of (17) to be

$$(I_1 D_1 - 2 D_2) D_1^2 + 2 D_1^3 D_2$$

$$(20). \quad D_1^2 (I_1 D_1 - 4 D_2).$$

Substituting these values for the determinants of (17) we get

$$(21). \quad M = 8 I_3 D_1^3 (I_1 D_1 - 4 D_2)$$

Or if we wish to make this of the proper degree in the Δ we have for the general case

$$(22). \quad M = 8 I_3 D_1^3 \Delta_1^3 (I_1 D_1 \Delta_1 - 4 D_2).$$

To express T similarly we can start with either of the minors from

$$(33). T = Q_{123}^2 - 4(Q_{121}Q_{131} + Q_{131}Q_{121} + Q_{111}Q_{232}) + 12(H)^2,^{**}$$

or the other form **

$$(24) T = (a'b'c'')^2 + 4(a'b'f'')(a'c'f'') + 4(b'c'g'')(b'a'g'') \\ + 4(c'a'h'')(c'b'h'') + 8(a'f'g'')(b'f'g'') + 8(a'f'h'')(c'f'h'') \\ + 8(c'f'g'')(b'g'h'') - 8(a'g'h'')(c'g'h'') - 8(b'h'f'')(a'h'f'') \\ - 8(c'f'g'')(a'b'h'') + 4(a'c'c'')(b'g'h'') - 8(f'g'h'')^2,$$

where

$$(a'b'c'') = a'b'c'' + a'b'c' + a'b'c + a'b'c + a'b'c + a'b'c,$$

and so for all similar forms.

In fact owing to the complicated algebra in either case it was deemed best to develop both independently,

which we will do in outline. Taking

$$(24) \text{ first we have from } U, V \text{ and } W$$

$$u, v, w = y, z = u^2, v^2, w^2 = uv, vw, wu = uv, vw, wu$$

$$u', v', c', f', g', h' = b_1^2, b_2^2, b_3^2, -b_1b_2, -b_2b_1, -b_1b_2$$

*

Conic Sections, p. 367.

** Ibid. p. 415.

$a, b, c, d, e, f, g, h, i, j, k, l, m, n, o, p, q, r, s, t, u, v, w, x, y, z$
 respectively. Making These substitu-
 tions directly in (24), and collect-
 ing the terms, which is a long task
 we have This expression

$$\begin{aligned}
 T = & \sum a_1^4 b_2^4 c_3^4 + 2 \sum a_1^4 b_2^2 b_3^2 c_2^2 c_3^2 + 2 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 \\
 & + 4 \left[2 \sum a_1^4 b_2^2 b_3^2 c_2^2 c_3^2 + \sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 - \sum a_1^4 b_2^2 b_3^2 c_2^2 c_3^2 \right. \\
 & \quad \left. - 2 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 - 3 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 \right] \\
 & + 8 \left[3 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 + 3 \sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 - \sum a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 \right. \\
 & \quad \left. - 2 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 - \sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 \right] \\
 & + 8 \left[\sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 + 3 \sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 \right. \\
 & \quad \left. - 4 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 - \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 \right] \\
 & + 4 \left[\sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 + \sum a_1^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 - \sum a_1^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 \right] \\
 & - 8 \left[\sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 + 2 \sum a_1^2 a_2^2 a_3^2 b_2^2 b_3^2 c_2^2 c_3^2 - 2 \sum a_1^2 a_2^2 b_2^2 b_3^2 c_2^2 c_3^2 \right].
 \end{aligned}$$

Collecting similar terms and us-
 ing the abbreviations of § 4, p. 30.

$$T = A - 4B + 4C + 4D + 6E + 28F - 4G - 40H + 6K.$$

Recalling from same paragraph
 $D_1^4 = A - 4B + 12C - 12D + 6E - 12F + 4G + 24H + 6K.$

$$D_1^2 I_2 = C - 2D + 2E - F + G + 4H.$$

$$D_2' = F + 2F \cdot H.$$

We have F finally obtained in the desired form,

$$(23) \quad F = D_1^4 - 8D_1^2 I_2 + 16D_2^2.$$

The above method is connected with long and tedious algebra, but is a very desirable verification of the form derived by starting with (23), i.e.

$$(23) \quad T = O_{23}^2 - 4(O_{22}O_{33} + O_{21}O_{33} + O_{31}O_{22}) + 12 \textcircled{H}$$

Recall what these O 's are as defined in Salmon. If one of a net of conics is

$$l(x)^2 + m(\beta x)^2 + n(\gamma x)^2 = 0,$$

and we write the discriminant

$$\begin{vmatrix} l\alpha_1^2 + m\beta_1^2 + n\gamma_1^2, & l\alpha_1\alpha_2 + m\beta_1\beta_2 + n\gamma_1\gamma_2, & l\alpha_1\alpha_3 + m\beta_1\beta_3 + n\gamma_1\gamma_3 \\ l\alpha_2\alpha_1 + m\beta_2\beta_1 + n\gamma_2\gamma_1, & l\alpha_2^2 + m\beta_2^2 + n\gamma_2^2, & l\alpha_2\alpha_3 + m\beta_2\beta_3 + n\gamma_2\gamma_3 \\ l\alpha_3\alpha_1 + m\beta_3\beta_1 + n\gamma_3\gamma_1, & l\alpha_3\alpha_2 + m\beta_3\beta_2 + n\gamma_3\gamma_2, & l\alpha_3^2 + m\beta_3^2 + n\gamma_3^2 \end{vmatrix}$$

then we can define:

Δ_{123} as the coefficient of l in the

the determinant.

O_{122} is the coefficient of $l m^2$, etc.

It is unnecessary to write out all the O 's for the general case. We shall write out one or two to illustrate the process.

$$O_{13} = \sum \alpha_1^2 \beta_2^2 \gamma_3^2 + 2 \sum \alpha_1 \alpha_2 \beta_3 \gamma_1 \gamma_2 - 2 \sum \alpha_1^2 \beta_2 \beta_3 \gamma_2 \gamma_3$$

Now for our conics U , V and W , we merely replace the O 's by the corresponding U , V and W , and observe that the product terms have different signs. That is $a_1 a_2$ must be replaced by $-a_1 a_2$, and so on.

This gives at once

$$O_{133} = \sum \alpha_1^2 \beta_2^2 \gamma_3^2 - 2 \sum \alpha_1 \alpha_2 \beta_3 \gamma_1 \gamma_2 - 2 \sum \alpha_1^2 \beta_2 \beta_3 \gamma_2 \gamma_3$$

which can at once be expressed in determinant form as

$$O_{133} = \begin{vmatrix} \alpha_1 & \alpha_2 & \alpha_3 \\ \beta_1 & \beta_2 & \beta_3 \\ \gamma_1 & \gamma_2 & \gamma_3 \end{vmatrix}^2$$

In transforming O_{122} and similar terms, care must be taken with the

sign of terms. For example when $\alpha_1 \beta_1$ is written β_1^2 , the sign would apparently be minus in the transformed form, i.e. $-\alpha_1 \beta_1^2$, whereas a study of its composition shows that it is actually $\alpha_1 \beta_1^2$. Observing this we get, writing

$$\begin{aligned} \theta_{122} &= \alpha_1^2 \beta_2^2 \beta_3^2 + \alpha_2^2 \beta_1^2 \beta_3^2 + \alpha_3^2 \beta_1^2 \beta_2^2 \\ &+ 2(\alpha_1 \alpha_2 \beta_3 \beta_2 \beta_1 \beta_3 + \alpha_2 \alpha_3 \beta_1 \beta_2 \beta_3 + \alpha_1 \alpha_3 \beta_2 \beta_1 \beta_3) \\ &- (\alpha_1^2 \beta_2 \beta_3 \beta_1 \beta_2 + \alpha_2^2 \beta_1 \beta_3 \beta_2 \beta_1 + \alpha_3^2 \beta_2 \beta_1 \beta_3 \beta_2) \\ &- 2(\alpha_1 \alpha_3 \beta_1^2 \beta_3 \beta_2 + \alpha_2 \alpha_3 \beta_1^2 \beta_3 \beta_2 + \alpha_2 \alpha_1 \beta_3^2 \beta_1 \beta_2), \end{aligned}$$

and replacing the Greek letters by the corresponding Roman ones, with sign changed as indicated, we have as a final form the following ternary

$$l_{122} = -4(a_1 a_2 b_1 b_2 b_3^2 + a_2 a_3 b_2 b_3 b_1^2 + a_3 a_1 b_3 b_1 b_2^2).$$

Similarly

$$l_{123} = -4(a_1 a_2 c_1 c_2 c_3^2 + a_2 a_3 c_2 c_3 c_1^2 + a_3 a_1 c_3 c_1 c_2^2).$$

$$l_{211} = -4(b_1 b_2 a_1 a_2 a_3^2 + b_2 b_3 a_2 a_3 a_1^2 + b_3 b_1 a_3 a_1 a_2^2).$$

$$l_{233} = -4(b_1 b_2 c_1 c_2 c_3^2 + b_2 b_3 c_2 c_3 c_1^2 + b_3 b_1 c_3 c_1 c_2^2).$$

$$l_{311} = -4(c_1 c_2 a_1 a_2 a_3^2 + c_2 c_3 a_2 a_3 a_1^2 + c_3 c_1 a_3 a_1 a_2^2).$$

$$\theta_{322} = -4(c_1 c_2 b_1 b_2 b_3^2 + c_2 c_3 b_2 b_3 b_1^2 + c_1 c_3 b_1 b_2 b_3^2).$$

Forming now from these the products required in (23) we get

$$\begin{aligned} \theta_{122} \theta_{133} = 16 & (\tilde{a}_1 \tilde{a}_2 b_1 b_2 b_3^2 c_1 c_2 c_3 + \tilde{a}_2 \tilde{a}_3 b_2 b_3 b_1^2 c_1 c_2 c_3 + \tilde{a}_3 \tilde{a}_1 b_1 b_2 b_3^2 c_1 c_2 c_3 \\ & + a_1 a_2 b_1 b_2 b_3 c_1 c_2 c_3 + a_2 a_3 b_2 b_3 b_1 c_1 c_2 c_3 + a_1 a_3 b_1 b_2 b_3 c_1 c_2 c_3 \\ & + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1^2 c_2^2 c_3^2 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1^2 c_2^2 c_3^2 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1^2 c_2^2 c_3^2). \end{aligned}$$

$$\begin{aligned} \theta_{211} \theta_{233} = 16 & (a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 \\ & + \sum_{i=1}^6 a_i^2 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3). \end{aligned}$$

$$\begin{aligned} \theta_{311} \theta_{322} = 16 & (a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 + a_1 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 \\ & + \sum_{i=1}^6 a_i^2 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3). \end{aligned}$$

Hence

$$\begin{aligned} & (\theta_{122} \theta_{133} + \theta_{211} \theta_{233} + \theta_{311} \theta_{322}) \\ & = 16 \left(\sum_{i=1}^6 a_i^2 a_2 a_3 b_1^2 b_2^2 b_3^2 c_1^2 c_2^2 c_3^2 + 3 \sum_{i=1}^6 a_i a_2 a_3 b_1^2 b_2^2 b_3^2 c_1 c_2 c_3 \right), \\ (25) \quad & = 16 \left[\frac{1}{4} (I_2^2 - D_2^2) + 3 I_1 I_3 \right] \\ & = 4 I_2^2 - 4 D_2^2 + 48 I_1 I_3. \end{aligned}$$

As a final step in expressing T , we must find an expression for Θ in terms of our invariants. Θ or Θ_{123} is defined by taking as the coefficient of x_1 in the discriminant of

$$l\Sigma + m\Sigma' + n\Sigma''.$$

Taking values of Σ , Σ' and Σ'' from (9) (10) and (11), The discriminant can be written down from Salmon's* determinant form as

$$8 a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3$$

$$\times \begin{vmatrix} 0 & la_3 + mb_3 + nc_3 & la_2 + mb_2 + nc_2 \\ la_3 + mb_3 + nc_3 & 0 & la_1 + mb_1 + nc_1 \\ la_2 + mb_2 + nc_2 & la_1 + mb_1 + nc_1 & 0 \end{vmatrix}$$

$$= 16 a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3 (la_1 + mb_1 + nc_1)(la_2 + mb_2 + nc_2)(la_3 + mb_3 + nc_3).$$

In this the coefficient of Σ is found to be

$$16 a_1 a_2 a_3 b_1 b_2 b_3 c_1 c_2 c_3 (a_1 b_2 + a_2 b_1 + a_3 b_2 + a_2 b_3 + a_3 b_1 + a_1 b_3).$$

$$= 16 I_3 I_1. \quad \text{So we have}$$

$$(26) \quad \Theta = 16 I_1 I_3.$$

Now substituting these values (24)

(25) and (26) in our expression (23) for

T we have

*

Conc Sections, p. 266.

$$T = (D_1^2 - 4I_2)^2 - 4(I_2^2 - D_1^2 + 4(I_1, I_2)) + 172 I_1 I_2.$$

(On collecting terms

(27) $T = D_1^4 - 8D_1^2 I_2 + 16D_2^2$ which is the same as the expression (25) obtained by the tedious expansion of (24).

We can now substitute the values (21) and (27) for M and T in Salmon's condition $T^2 = 64M$ and have as a final Theorem:-

If the 3-point and the 3-line are such that a conic may be inscribed in the 3-line and circumscribed about the 3-point, then

$$(D_1^4 - 8D_1^2 I_2 + 16D_2^2)^2 - 512 I_2 D_1^3 (I_1 D_1 - 4D_2) = 0.$$

If we now apply the dual transformation to (28) we get another theorem which leads to some interesting conclusions. The dual form is

$$[D_1^8 - 8D_1^4(D_1^2 I_2 - 2I_1 D_1 D_2 + 6D_2^2) + 16D_1^4 D_2^2]^2$$

$$- 512 D_1^6 (D_1^3 I_3 - D_2^3 + \frac{1}{2} I_1 D_1 D_2^2 - \frac{1}{2} I_2 D_1^2 D_2) (I_1 D_1^3 - 2D_1^3 D_2) = 0$$

Expanding and collecting, This becomes

$$(29). D_1^8 [D_1 (D_1^4 + 64 I_2^2 + 32 I_1 D_1 D_2 - 16 D_1^2 I_2 - 64 D_2^2)$$

$$- 512 I_3 (I_1 D_1 - 2 D_2)] = 0.$$

Hence The dual Theorem reads:-

A conic can be drawn on the
meets of the 3-lines and touching
the joins of the 3-point if (29) = 0.

It may be noted in this section, that no reference has been made to the introduction of Δ_1 , so as to render the forms general. In fact it is scarcely necessary, for obviously in (28) there will be no extraneous factor Δ_1^6 . Hence all we have to do, is to mechanically place in that individual term the proper power of Δ_1 to make the expression homogeneous. Whence thus it becomes

$$(30). (D_1^4 \Delta_1^4 - 8 D_1^2 \Delta_1^2 I_2 + 16 D_1^2)^2 - 512 I_3 D_1^3 \Delta_1^3 (I, D, \Delta_1 - 4 D_2) = 0$$

Since (30) is the same as (28) considered previously, hence we would have

$$(1) D_1^4 \left[1, \Delta_1, (1, D_1^2 \Delta_1^2 - 4 I_2) - 1, D, \Delta_1, D_1^2, 16 D_1^3 \Delta_1^3, 64 I_3 \right. \\ \left. - 512 I_3 (I, D, \Delta_1 - 2 D_2) \right] = 0.$$

It is to be noted that the essential factor of (31) is the quintic factor in the square brackets. The other factor merely expresses the fact that the construction is always possible if the three points are on a line.

We shall next consider (28) and (29) under the special condition that two of points of the 3-point are taken as I and J , the circular point at infinity, and the third point is taken as a variable point x . Then (28) and (29) become equations of the 8th and 5th degree respectively. It is this 8th and this quintic which

we shall discuss briefly. We shall designate them by Λ and Q respectively. That is

$$\Lambda = (D_1^4 - 8D_1^2 I_2 + 16D_2^2)^2 - 512 I_3 (I_1 D_1 - 4D_2) = 0$$

$$Q = D_1 (D_1^4 + 64 I_2^2 + 32 I_1 D_1 D_2 - 16 D_1^2 I_2 - 64 D_2^2)$$

$$- 512 I_3 (I_1 D_1 - 2 D_2) = 0$$

where we understand b_c and c_c are replaced by the coordinates of I and J , and a_c by x_c .

In the case of conics on the 3-line and on the 3-points, if two of the points are taken at I and J , obviously all the conics become circles on the 3-line, i.e. touching the three lines. In other words $R=0$, is merely the locus of points, from which circles can be drawn, touching the three lines of the 3-line. This in turn says that $R=0$ is simply the equation of the four circles which



touch the three lines
and are shown in
the adjoining figure
being very easily
constructed.

If we look at Q , we see that
we have a quintic equation. In this
case the conics ~~touches~~ the line join-
ing I and J , - the line at infinity.
Hence they are parabolas. Further
the lines joining I and J to x are
tangents to the corresponding para-
bolas. Hence x being the meet of
the tangents from I and J is
the focus. So we know the theo-
rem:-

The locus of the foci of all
parabolas on three points is a
quintic curve, and if the three

Point Q is taken as the vertex of the reference triangle. The equation of this quadratic locus is

$$Q = 0.$$

It is possible to read off some facts in regard to R and Q without writing out the explicit equations, although the above method gives a rather simple way of doing that. It is well to note first what curves are represented by certain simple equations when as above two points are taken at I and J and the third vertex.

$I_3 = 0$, is equation of reference triangle.

$D_1 = 0$, is equation of the line at infinity.

$I_1 = 0$, is equation of the polar line of I and J as to the triangle.

$U_2 = 0$ is equation of circumcircle.

$I, D_1 - 2 D_2 = 0$, is equation of The apollonius circle.

$I, D_1 - 4 D_2 = 0$ is Feuerbach circle.

Of these forms, none require any special proof except possibly the last. By Hux*, the equation of The Feuerbach conic, or in the present case The Feuerbach circle is $N = 0$. But we saw $-N = I, D_1 - 4 D_2$. Or it can be shown directly from the fact that $I, D_1 - 4 D_2$ is the locus of centers of rectangular hyperbolas on the vertices of the \triangle . But the



feet of The 3 perpendiculars are clearly centers of such hyperbolas. But They are also points of The 9-point or Feuerbach circle. Hence since $I, D_1 - 4 D_2$ is a circle it must be the Feuerbach circle.

* Page 47. See note.

Now take the equation

$R = [D_1^4 - 8D_1^2 I_2 + 16D_2^2] - 3I_3 D_1^3 (I_1 D_1 - 4I_2) = 0$,
which we know is the equation of the
four touching circles.

If $I_3 = 0$, $(D_1^4 - 8D_1^2 I_2 + 16D_2^2) = 0$, Hence
 $I_3 = 0$, The reference triangle touches
the octavic, where it (the reference
triangle) cuts the quartic, $D_1^4 - 8D_1^2 I_2 + 16D_2^2 = 0$.

If $I_1 = 0$, $(D_1^4 - 8D_1^2 I_2 + 16D_2^2) = 0$, which
merely says that the quartic passes
through the multiple point of R ,
where the line at infinity cuts.

If $I_1 I_2 - 4I_3 = 0$ the same quartic
squared equals zero. Hence the
Steinerbach circle touches the oc-
tavic, ^{or passes through double points,} where it is cut by the qua-
tic, $D_1^4 - 8D_1^2 I_2 + 16D_2^2 = 0$. This is
a verification of the well known
theorem that the Steinerbach circle
touches the inscribed and escribed

curves.

The question which comes up in this connection is pretty interesting in itself. Taking its equation $K = L_1^2 + 8L_1L_2 + 16L_2^2 = 0$, we see that when $L_1 = 0$, $L_2 = 0$, which with earlier considerations, shows that K is a bicircular quartic. We know all its intersections with the octavic; - 12, where the reference triangle touches the octavic, 4, where the Feuerbach circle touches it, and 8 at each circular point at infinity. But it is not of importance for our purpose to discuss this quartic in detail. The conic, $D_1^2 - 8I_2 = 0$, which is met at several places is probably also of slight geometrical interest. As itself being completely known, we will take up K briefly.

Taking the form

$$(32) Q = 4_1 [I_1^2 - 3I_2 + 32I_3, I_1, I_2, (4I_3)^2 - 512I_3(I_1I_2 - 2D_2)] = 0$$

we can abbreviate by setting

$$D_1^2 - 8I_2 = U$$

$16(I_1I_2 - 2D_2) = V$, where $U=0$, $V=0$ are lines. We have then

$$(33) Q = 4_1 (U^2 - D_2V) - 32I_3V = 0$$

If in this $D_1=0$, then $I_3V=0$, that is Q cuts the line at infinity in the five points where I_3 and V cut it. But $I_3=0$ is the reference triangle and $V=0$ is the apolar circle. Hence

The quintic $Q=0$, passes through the circular points at infinity, and has its asymptotes parallel to the sides of the reference triangle.

Again if $V=0$, $I_1I_2=0$, which says that $V=0$, the apolar circle touches the quintic, or cuts it at the two points where U and V intersect.

sent. Since Q was to prove as
 true, and its six double points
 would not all generally lie on a con-
 ic, it follows that V does not cut
 Q in double points. Hence the
 theorem:

The apolar circle $V=0$, has
 four-fold contact with the quartic
 $Q=0$, touching it at the four
 points where $U=0$ and $V=0$.

This same fact can be proved
 more directly by taking the dual
 of $V=0$, which turns out to be

$$I, U_1 - 4U_2 = 0, \text{ say } F=0$$

and we have proved this to be the
 Feuerbach circle. But it is a well
 known theorem that the Feuerbach
 circle of any triangle touches each
 of the four tangent circles. It has
 as $F=0$, touches $U=0$ in four points

As we can see that Q is not destroyed in taking the dual. In a sense Q is the dual of R , and V of F , it follows that V touches Q at four points, which was the theorem to be proved.

Suppose we rewrite Q thus

$$(34) \quad Q = D_1 U^2 + 2V(D_1 D_2 - 16 I_3) = 0$$

$$\text{or } = D_1 U^2 + 2VW = 0$$

$W=0$ is a cubic meeting the line at infinity where the sides of the reference triangle meet it and passing through the vertices of the reference triangle. Therefore we have the theorem

$W=0$ touches Q where V cuts W .

Of course these contacts are real or imaginary according as the intersections of U and V are real or imaginary. This remark applies elsewhere.

We can also in this way find where $Q=0$, cut the circumcircle. For in Q , let $D_2=0$ and it becomes

$$(35) \quad D_1(D_1^2 - I_2) - 5/12 I_1 I_3 = 0$$

so unless the 3 points are on a line

$$(36) \quad (D_1^2 - 8 I_2)^2 - 5/12 I_1 I_3 = 0$$

Also in $R=0$, let $D_2=0$ and it becomes $(D_1^4 - 8 D_1^2 I_2)^2 - 5/12 I_1 I_3 D_1^4 = 0$ or dropping D_1^4 as a factor,

$$(37) \quad (D_1^2 - 8 I_2)^2 - 5/12 I_1 I_3 = 0. \quad = (36).$$

Hence the Theorem, -

Q and R cut the circumcircle in the same points.

If the triangle is real, six of these points are always real and can be constructed very easily. We will not go into any further discussion of this or other loci problems. But there is one very im-

mediate and simple remark which may be made. It concerns the question of whether a locus, obtained by allowing one point to vary, is on the fundamental points or not. The term fundamental points here applies to both the ^{fixed} points of the 3-point and meets of the 3-lines. If a locus is on a fundamental point, it denotes that if my variable point coincides with that fundamental point, the invariant condition is satisfied. To illustrate this take the fundamental invariants:-

$D_1 = 0$, is the equation of the join of the two fixed points, hence D_1 vanishes if the movable point coincides with a fixed point but does not vanish due to a coincidence of x with a meet of the 3-lines.

Similarly.

I_1 vanishes at no time, due to a coincidence of x with a fundamental point.

D_2 vanishes if x coincides with a point of the F line, and also if it coincides with a fixed point.

I_2 does not vanish due to any coincidence of x with a fundamental point.

I_3 vanishes if x is anywhere on any of the three lines, but not when it coincides with a fixed point.

These facts are of importance at times as they enable us to tell whether a certain invariant vanishes because of a particular position of one point, or whether the vanishing or non-vanishing of the invariant is unaffected by such coincidence. For instance

we know that any invariant built
 up of terms containing a D , or a D_2
 are each of them, if ^{considered} two of the points
 coincident, while any invariant built
 up of combinations of I , and I_2 , will
 not vanish if two points are taken co-
 incident, nor if each point is taken
 as a vector or used of the 3 lines.

§ 8. The Clebschians and their Invariants.

In the case of two general line cubics, the Clebschian has been defined analytically thus. Let $(ax)^3$ and $(bx)^3$ be the cubics, then

$$(1) \quad X = 12abx^3$$

is the Clebschian or intermediate.

If we were now to write the point equations of the ~~two~~ same two cubics, say $(ax)^3$ and $(\beta x)^3$, we would in an entirely analogous manner define the line cubic

$$(2) \quad X' = 12\beta\beta x^3 = 0$$

is the Clebschian of the two point cubics. In general X and X' are not the same for two triangles.

In forming Clebschians, it is obvious that we must take both tri-

angles in points (and both in lines), in this section. Of course the line equation $2E, x_2 x_3$, has as its equation in line coordinates $f_2 x_2 + f_3 x_3 = 0$. Hence starting with one cubic as the reference triangle, and the other as a general cubic $(a_3)^3 = 0$, we have by simply substituting in the expanded form of (1)

$$(3). \chi = 6(a_1^2 a_3^2 x_1^2 x_2 + a_1^2 a_2^2 x_1^2 x_3 + a_1^2 a_3^2 x_1^2 x_3 - a_1 a_2^2 x_1 x_2^2 - a_1^2 a_2 x_1 x_2 x_3 - a_1^2 a_3 x_1^2 x_3).$$

If now the second cubic is taken as the 3-point $(a_3)(b_3)(c_3)$, we must replace

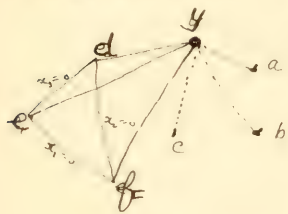
$$3a_1 a_3^2 \text{ by } (a_2 b_3 c_3 + a_3 b_2 c_3 + a_3 b_3 c_2)$$

$$3a_1 a_2^2 \text{ by } (a_1 b_2 c_2 + a_2 b_1 c_2 + a_2 b_2 c_1) \text{ etc}$$

Hence we have

$$(4) \chi = 2[(a_2 b_3 c_3 + a_3 b_2 c_3 + a_3 b_3 c_2)x_1^2 x_2 + (a_1 b_3 c_3 + a_3 b_1 c_3 + a_3 b_3 c_1)x_1^2 x_3 + (a_3 b_1 c_1 + a_1 b_3 c_1 + a_1 b_1 c_3)x_2^2 x_3 - (a_1 b_3 c_3 + a_3 b_1 c_3 + a_3 b_3 c_1)x_1 x_2^2 - (a_1 b_1 c_1 + a_1 b_3 c_3 + a_3 b_1 c_3)x_1 x_2 x_3 - (a_1 b_3 c_3 + a_3 b_1 c_3 + a_3 b_3 c_1)x_1^2 x_3].$$

Before going further it may be desirable to fix the idea of the Clebschian of two triangles. When



The triangles are both taken as 3-points. The Clebschian may be defined as the

locus of points y such that the two triads of lines $y-a$ and $y-def$ are isogonal. The other Clebschian is the locus of lines η having the dual property. From (14) we can read directly some of the properties of this curve. Since it does not contain any cubic terms, it is on the vertices of the reference triangle, and from the symmetry — the relation in the general case, — we have the theorem —

The Clebschian of two 3-points
is a cubic curve on the 10-points.

Again since the Clebschian has no term in $x_1 x_2 x_3$, it follows that the reference triangle is apolar to it. Hence since both triangles enter the sum we have.

The Clebschian of two 3-points
is a cubic curve to which both
3-points are apolar.

The dual theorem holds for the Clebschian of two 3-lines.

Going back to (4) we shall next express the invariants S and T of this cubic in terms of our fundamental system. This must clearly be possible for S and T are also invariants of the original triangles.

We shall make use of

form * for 5

$$\begin{aligned}
 (5) \quad S = & a b c m (t c a_2 a_3 + c a b_1 b_3 + a b_1 c_1 a_2) \\
 & - m (a b_1 c_2 + c a_2 b_1 c_1) + (a b_1 c_2^2 + c a_2^2 c_1^2 \\
 & + a c_1 b_1^2 + b a_3 c_1^2 + c b_3 a_2^2 + a_3 b_1^2) - m^2 + 2 m^2 (b_1 c_1 \\
 & + c_2 a_2 + a_3 b_3) - 3 m (a_2 b_3 c_1 + a_3 b_1 c_2) - (b_1^2 c_1^2 + c_2^2 a_2^2 + a_3^2 b_3^2) \\
 & + (c_2 a_2 a_3 b_3 + a_3 b_3 b_1 c_1 + b_1 c_1 c_2 a_2) .
 \end{aligned}$$

On the corresponding differentials

$$d\lambda = 4d\alpha + 2d\beta$$

$$d\alpha = (a_2 b_3 c_3 + a_3 b_2 c_3 + a b c) .$$

$$d\alpha_3 = -(a_3 b_1 c_1 + b_1 c_1 a_2 b_3) .$$

$$db_1 = -(a_1 b_3 c_3 + a_3 b_1 c_3 + a_3 b_3 c_1) .$$

$$db_3 = (a_3 b_1 c_1 + a_1 b_3 c_1 + a_1 b_1 c_3) .$$

$$dc_1 = -(a_2 b_1 c_1 + a_1 b_2 c_1 + a_1 b_1 c_2) .$$

$$dc_2 = (a_2 b_3 c_2 + a_3 b_1 c_2 + a_2 c_1 c_2) .$$

$$dc_3 = (a_1 b_3 c_3 + a_3 b_1 c_3 + a_2 c_1 c_3) .$$

It will be observed that we have dropped the common non-essential numerical factor. Making

the above identifications on (5)

* Hohen & Ebiner Curves, 1924

$$\begin{aligned} (c) \quad S = & -(a_1b_1c_1 + a_2b_1c_1 + a_3b_1c_1)(a_1b_2c_1 + a_2b_2c_1 + a_3b_2c_1) \\ & - (a_2b_1c_2 + a_3b_1c_2 + a_3b_2c_2)(a_3b_1c_1 + a_1b_2c_1 + a_1b_3c_1) \\ & - (a_3b_2c_2 + a_2b_3c_2 + a_2b_2c_2)(a_3b_1c_1 + a_1b_3c_1 + a_1b_3c_1) \\ & + (a_2b_1c_3 + a_3b_2c_3 + a_3b_3c_3)(a_2b_1c_1 + a_1b_2c_1 + a_1b_2c_2) \\ & (a_3b_2c_2 + a_2b_3c_2 + a_2b_2c_2)(a_3b_1c_1 + a_1b_3c_1 + a_1b_3c_1) \\ & + (a_3b_2c_2 + a_2b_3c_2 + a_2b_2c_2)(a_3b_1c_1 + a_1b_3c_1 + a_1b_3c_1) \\ & (a_1b_3c_3 + a_3b_1c_3 + a_3b_3c_1)(a_1b_2c_2 + a_2b_1c_2 + a_2b_2c_1) \\ & + (a_1b_3c_3 + a_3b_1c_3 + a_3b_3c_1)(a_1b_2c_2 + a_2b_1c_2 + a_2b_2c_1) \\ & (a_2b_1c_1 + a_1b_2c_1 + a_1b_2c_2)(a_2b_3c_3 + a_3b_2c_3 + a_3b_3c_2) \end{aligned}$$

The actual work of expanding and collecting the terms in (6) is long but the result can be very concisely expressed, for many terms cancel: -

$$(.) \quad S = 16_1 \int^{18} (a_1^2 a_2^2 a_3^2 - \int^9 (a_1^2 a_2^2 a_3^2 a_4^2 a_5^2 a_6^2 a_7^2 a_8^2 a_9^2 a_{10}^2 a_{11}^2 a_{12}^2 a_{13}^2 a_{14}^2 a_{15}^2 a_{16}^2 a_{17}^2 a_{18}^2) - \sum^9 a_1^4 a_2^2 a_3^2 a_4^2 a_5^2 a_6^2 a_7^2 a_8^2 a_9^2) \cdot$$

We can here again use the summation symbols of § 4 to advantage, for we have

$$(5) \quad S = 16(C - H - R) .$$

We observe that the D_i 's must enter to an even degree (or not at all) in every term. Combining the equalities found § 4, page 30 we find the only combinations required were

$$I_2(D_1^2 + D_2^2) = 2C + 4E + 16F + 2G + 4H = P$$

$$I_2^2 D_2^2 = 4H = P'$$

$$(I_1^2 D_1^2)^2 = 32C + 64H + 16K = P''$$

$$I_1 D_1 D_2 = -C + 2E + 5F + G - 4H = P'''$$

It remains to properly choose coefficients, which is relatively easy, being the solution of many simple differential equations for expression in σ of type

$$(1) \quad \lambda P + \mu P' + \nu P'' + \rho P'''$$

It turns out ^{that} $\lambda = 12$, $\mu = -36$, $\nu = 1$
and $\rho = -24$

We can verify this directly by putting these values of λ, μ, ν, ρ in (1) and showing that the result is zero.

$$12 P_1 = 24C + 48E + 120F + 24G + 96H$$

$$24 P'' = 24C + 48E + 120F + 24G + 96H$$

$$-36 P' = -144H$$

$$- P'' = -32C - 64H - 16I$$

$$\therefore 12P - 6P' - P'' - 24P'' = 16C - 16H - 16I = 0.$$

or,

$$(10). S = 12 I_2 (D_1^2 + I_1^2) - 36 (I_1^2 - D_1^2) - (I_1^2 - I_1^2)^2 - 24 I_1 D_1 D_2$$

where $S = 0$, is the condition that the Steiner of the Clebschian is three lines.

Owing to the fact that the Clebschian treats the two triangles symmetrically, it is clear that S should be self-dual and a trial as to the truth of this is a good check on the work. The dual is

$$(11) S' = 12 (I_2 D_1^2 - 2 I_1 D_1 D_2 + 6 D_2^2) (D_1^4 + I_1^2 I_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2) \\ - 36 [(D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2)^2 - D_1^4 D_2^2] - (I_1^4 D_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2 - D_1^4)^2 \\ + 24 (I_1^2 D_1^2 - 6 D_2^2) D_1^4 D_2^2$$

$$(12) = D_1^4 S.$$

To express S in somewhat more concise form we can write it as the difference of two squares,
 (13). $S = 4(I, D_1 - 3D_2)^2 - (I_1^2 + D_1^2 - 6I_2)^2$.

$I, D_1 - 3D_2$ is one of three self dual forms, and in the special case where two points are taken, it is I and S and the third case, it is the circle having the join of the two centers and the centroid as a diameter.

The invariant I of a cubic curve is written out in full by Salmon* for the general case. If we substitute the coefficients of χ the Clebschian directly into the form there given, and attempt to express the result, by direct processes in terms of our invariants, the algebra becomes very cumbersome if not entirely unmanageable. See our paper etc.

manageable. The following method includes not only the case, presents you fewer difficulties.

Take at the outset one reference triangle, and the other as a general cubic, in Salmon's form

$$(4). \quad a\xi_1^3 + b\xi_2^3 + c\xi_3^3 + 3a_2\xi_1^2\xi_2 + 3a_3\xi_1^2\xi_3 + 3b_1\xi_1\xi_2^2 + \\ + 3b_2\xi_1\xi_3^2 + 3c_1\xi_2^2\xi_3 + 3c_2\xi_2\xi_3^2 + 6m\xi_1\xi_2\xi_3.$$

Now following Clebsch, we will write the connex set up by two general cubics $(\alpha x)^3$ and $(\alpha \xi)^3$,

$$(\alpha a)^2(\alpha x)(\alpha \xi) = 0$$

and follow his method of getting the invariants of the connex. The fixed points of the connex are given by the three equations

$$(5). \quad a_c(\alpha x)(\alpha a)^2 = \lambda x_c \quad c = 1, 2, 3.$$

which requires in order to be consistent that $\Delta(x)$ vanish, which

$$(16) \quad \Delta(\lambda) = \begin{vmatrix} a_1 \alpha_1 (\alpha a)^2 + \lambda & a_2 \alpha_1 (\alpha a)^2 & a_3 \alpha_1 (\alpha a)^2 \\ a_1 \alpha_2 (\alpha a)^2 & (a_2 \alpha_2) (\alpha a)^2 + \lambda & a_3 \alpha_2 (\alpha a)^2 \\ a_1 \alpha_3 (\alpha a)^2 & (a_2 \alpha_3) (\alpha a)^2 & a_3 \alpha_3 (\alpha a)^2 + \lambda \end{vmatrix}$$

And the invariants of the curves are the coefficients of the powers of λ in the expansion of this determinant, and are in fact the particular invariants (in the case of two curves) discussed by Dr. Hux.

As soon as one of the cubics is taken as the reference 3-line, (16) reduces to

$$(17) \quad \Delta(\lambda) = \begin{vmatrix} 2a_1 a_2 a_3 + \lambda & 2a_1^2 a_3 & 2a_1 a_3^2 \\ 2a_1^2 a_3 & 2a_1 a_2 a_3 + \lambda & 2a_1 a_3^2 \\ 2a_1^2 a_2 & 2a_2^2 a_1 & 2a_1 a_2 a_3 + \lambda \end{vmatrix}$$

If now our second cubic is taken in the form, instead of in the symbolic form, symbolic products must be replaced as follows in $\Delta(\lambda)$

$$a_1, a_2, a_3 \text{ by } m,$$

$$a_1^2, a_1 \text{ by } c_1,$$

$$a_2^2, a_2 \text{ by } b_1,$$

$$a_1^2, a_1 \text{ by } a_2,$$

$$a_1, a_1^2 \text{ by } c_2,$$

$$a_2^2, a_1 \text{ by } b_1,$$

$$a_1^2, a_2 \text{ by } a_3$$

With these substitutions

$$(18) \quad f(\lambda) = \begin{vmatrix} m + \lambda & a_3 & a_2 \\ b_3 & m + \lambda & b_1 \\ c_2 & c_1 & m + \lambda \end{vmatrix}$$

$$(19) = \lambda^3 + J_1 \lambda^2 + J_2 \lambda + J_3, \quad \text{where}$$

$$J_1 = 3m.$$

$$J_2 = 3m^2 - (b_1 c_1 + c_2 a_2 + a_3 b_3).$$

$$J_3 = \begin{vmatrix} m & a_3 & a_2 \\ b_3 & m & b_1 \\ c_2 & c_1 & m \end{vmatrix} = m^3 + a_3 b_1 c_2 + a_2 b_3 c_1 - m(b_1 c_1 + c_2 a_2 + a_3 b_3).$$

It is quite customary to write equations like (11) with different signs, but there appears to be no necessity, but an apparent disadvantage in so doing. In expressing T , it is convenient to use these invariants.

and also S in the form at issue when in (5), we let $a = b = c = m$

$$\text{i.e. } S = -(b_1^2 c_1^2 + c_2^2 a_2^2 + a_3^2 b_3^2) + c_2 a_2 a_3 b_3 + a_3 b_3 b_1 c_1 + b_1 c_1 c_2 a_2.$$

To avoid we will use $I_1 = m$, instead of I_1 . This is the I_1 of the present system so is doubly convenient.

Now Take X , The Clebschian,

$$c_2 x_1^2 x_2 + b_1 x_1 x_3^2 + a_3 x_2^2 x_3 - c_1 x_1 x_2^2 - a_2 x_3^2 x_2 - b_3 x_1^2 x_3 = 0$$

and compare it with Salmon's general form. First of all $a = b = c = m = 0$,

and this at once causes T to assume the very simple form

$$(20). T = -6 b_1 c_1 a_2 a_3 b_3 + 2(a_1^3 c_1^3 + c_2^3 a_2^3 + a_3^3 b_3^3) - 27(a_1^2 b_1^2 c_1^2 + c_2^2 b_2^2 c_2^2) \\ 12(b_1^3 c_1^3 a_2 + c_2^3 a_2^3 b_3 + a_3^3 b_3^3 c_1 + 2b_1^3 + 2c_2^3 + 2a_3^3)$$

Comparing further we find we must

have

$$a_2 \text{ by } c_2,$$

$$a_3 \text{ by } -b_3$$

$$b_3 \text{ by } a_3,$$

$$b_1 \text{ by } c_1$$

$$c_1 \text{ by } b_1,$$

$$c_2 \text{ by } -a_2.$$

Making these substitutions in (20) becomes

$$(2) T = 6b_1c_1c_2a_1b_1 - 8(b_1c_1^2 + c_1a_1^2 + a_1b_1^2) - 27(a_1b_1c_1^2 + a_1b_1^2c_1) \\ + 12(b_1^2c_1^2c_2 + 5c_1^2a_1c_2 + c_1a_1^2c_2 + c_1^2b_1^2 + 2c_1b_1^2a_1 + 2b_1^2c_1a_1).$$

which we may for brevity write

$$T = 6x - 8y - 17z + 12t.$$

We can now express T in terms of I_1, I_2, I_3 and S . Without going into the logic, the following combinations suggest themselves,

$$(3I_1^2 - I_2)^3 = \sum b_1^3c_1^3 + 3\sum b_1^2c_1^2a_1 + 6b_1c_1c_2a_1b_1 = 6x + y + 3t$$

$$(I_3 + 2I_1^3 - I_1I_2)^2 = a_1^2b_1^2c_1^2 + a_1^2b_1^2c_2^2 + 2b_1c_1c_2a_1b_1 = 2x + 2z$$

$$S(3I_1^2 - I_2) = -\sum b_1^3c_1^3 + 3b_1c_1c_2a_1b_1 = 3x + y,$$

and from these T is found at once by a proper choice of coefficients. It remains to

$$(3) T = 4(3I_1^2 - I_2)^3 - 27(I_3 + 2I_1^3 - I_1I_2)^2 + 12S(3I_1^2 - I_2).$$

Expanding terms and collecting

$$(3) T = 54I_1I_2I_3 + 7I_1^4I_2^2 - 27I_3^2 - 4I_1^5 - 108I_1^3I_3 + 12S(3I_1^2 - I_2).$$

Now I_2, I_3 and S must be replaced by their equivalents, which have already been derived. For simplicity T_2

and I_3 are nothing but I_1 and $-I_2$ respectively. Hence

$$I_2 = 2(I_1^2 + D_1^2) + 12 I_2$$

$$I_3 = D_1(4 I_2^2 + I_1 D_1),$$

$$S = 12 I_2 (D_1^2 + I_1^2) - 24 I_1 D_1 D_2 - 36 (I_1^2 - D_1^2) - (I_1^2 - D_1^2)^2.$$

Carrying these over

$$(14). T = 4(I_1^2 - D_1^2 + 12 I_2)^3 - 27(4 I_1 D_1^2 + 12 I_1 I_2)^3 \\ + 12(12 I_2 D_1^2 + 12 I_2 I_1^2 - 24 I_1 D_1 D_2 - 36 I_2^2 + 36 D_2^2 \\ - I_1^4 + 2 I_1^2 D_1^2 - D_1^4)(I_1^2 - D_1^2 + 12 I_2)$$

Expanding and collecting terms

$$(15) T = -8 I_1^6 + 144 I_1^4 D_1^2 + 144 I_1^2 D_1^4 - 1728 I_2^3 - 144 I_1 I_2 \\ - 864 I_1^2 I_2^2 - 144 D_1^4 I_2 + 432 D_1^2 I_2^2 - 288 I_1^3 D_1 D_2 \\ + 288 I_1 D_1^3 D_2 + 432 I_1^2 D_2^2 - 864 D_1^2 D_2^2 - 864 I_1 I_2 D_1 D_2 + 5184 I_2 D_2^2.$$

Or grouping terms, $T =$

$$(26) -8[(I_1^2 - D_1^2)^3 - 216 I_2^3 - 18 I_2 (I_1^4 - D_1^4) + 108 (I_1^2 I_2^2 + D_1^2 D_2^2) \\ - 54 (D_1 I_2 - I_1 D_2)^2 + 36 I_1 D_1 D_2 (I_1^2 - D_1^2) - 648 I_2 D_2^2].$$

Just as S was necessarily a perfect square, so must T be, if the result is correct. Carrying out the formation of the discriminant

$$\begin{aligned}
T' = & (I_1^2 D_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2 - D_1^4)^3 - 216 (D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2)^3 \\
& - 18 (D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2) (I_1^4 D_1^4 - 24 I_1^3 D_1^3 D_2 + 216 I_1^2 D_1^2 D_2^2 \\
& - 864 I_1 D_1 D_2^3 + 1216 D_2^4 - I_1^4) \\
& + 108 \left[(I_1^2 D_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2) (D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2) - 3 I_1 D_1 D_2^2 \right] \\
& - 54 \left[D_1^2 (D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2) + D_1^4 D_2 (I_1 D_1 - 6 D_2) \right]^2 \\
& - 36 D_1^4 D_2 (I_1 D_1 - 6 D_2) (I_1^2 D_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2 - D_1^4) \\
& - 64 I_1^4 I_2^2 (D_1^2 I_2 - 2 I_1 D_1 D_2 + 6 D_2^2) ;
\end{aligned}$$

Expanding and collecting

$$\begin{aligned}
& = I_1^6 D_1^6 - D_1^{12} - 3 I_1^4 D_1^8 - 54 I_1^2 D_1^6 D_2^2 + 3 I_1^2 D_1^{10} - 36 I_1 D_1^9 D_2 \\
& + 16 I_1^4 D_2^2 + 16 I_1^2 I_2^2 D_2 - 16 I_1^6 I_2^3 - 16 I_1^4 I_1^6 + 1 I_1 D_1^{10} \\
& - 108 I_1^2 I_2^2 D_1^6 - 54 D_1^8 I_2^2 - 648 I_2 D_1 D_2^2 + 108 I_1 I_2 D_1^7 D_2 . \\
& = D_1^6 T .
\end{aligned}$$

So T is obtained, being a relation of the coordinates of the line ST .

Knowing S and T we can immediately write down the discriminant of the Clebschian in terms of our invariants, since it is merely $T^2 + 64 S^3$. The general case of two triangles in general position, the underlying

long and unattractive. If however the two triangles are taken as inscribed in a conic, the form is much simplified for then $D_2 = 0$. Calling the discriminant D ,

$$D = 64 I_2^2 D_1^2 (5 I_1^4 D_1^2 - 324 I_1^2 I_2^2 - 3 I_1^6 - I_1^2 D_1^4 + 521 I_1^4 I_2 + 48 I_1 I_2 D_1^2 - D_1^6 + 26 I_2 D_1^4 - 225 D_1^2 I_2^2 + 645 I_2^3).$$

Before taking up χ' , the line Ptolemaean, and its invariants, which really present little of importance, we will look for the invariant condition that the two triangles that the conic has to satisfy.

Taking any triangle as the first triangle, to all, or any, of the other triangles (the first Ptolemaean is then as we had in equation (4)

$$(27). \quad \chi = (a_1 b_1 c_1 + a_2 b_2 c_2 + a_3 b_3 c_3) x_1 x_2 + (a_1 b_1 c_2 + a_2 b_2 c_3 + a_3 b_3 c_1) x_1 x_3 \\ + (a_2 b_1 c_1 + a_1 b_3 c_1 + a_1 b_1 c_3) x_2 x_3 - (a_1 b_3 c_3 + a_3 b_1 c_3 + a_3 b_3 c_1) x_1 x_2^2 \\ - (a_2 b_1 c_1 + a_1 b_3 c_1 + a_1 b_1 c_3) x_2 x_3^2 - (a_3 b_1 c_1 + a_2 b_3 c_2 + a_2 b_3 c_3) x_1^2 x_3.$$

If we now take my triangles as 3-series, that is with the point equations, the only effect on the coefficients in the second triangle, χ' , will be to replace each letter, by its minor in D . Of course the coordinates will be line coordinates, and the triangle a related reference triangle. Representing the minors by the corresponding Capitals we have

$$(28) \quad \chi' = (A_2 B_1 C_2 + A_1 B_2 C_1 + A B C) \xi_1 \xi_2 + (A_1 B_2 C_2 + A B_1 C_1 + A B C) \xi_1 \xi_2^2 \\ + (A_2 B_1 C_1 + A_1 B_2 C_2 + A B C) \xi_1 \xi_2 - (A_1 B_2 C_3 + A B_1 C_2 + A B_2 C_1) \xi_1 \xi_2^2 \\ + (A_2 B_1 C_2 + A B_2 C_1 + A B C) \xi_2 \xi_1^2 - (A B C_2 + A B_1 C_2 + A B_2 C_1) \xi_1^2 \xi_3.$$

Now to find the up-to- γ condition we will regard the ξ 's as differential operators, and equate the result of the operation to zero. This gives

$$\begin{aligned}
(29). & (a_1 b_1 c_1 + a_2 b_1 c_2 + a_3 b_1 c_3) (A_1 B_1 C_1 + A_1 B_2 C_2 + A_1 B_3 C_3) \\
& + (a_1 b_1 c_2 + a_2 b_1 c_3 + a_3 b_1 c_1) (A_1 B_2 C_1 + A_1 B_3 C_2 + A_1 B_1 C_3) \\
& + (a_1 b_2 c_1 + a_2 b_2 c_2 + a_3 b_2 c_3) (A_2 B_1 C_1 + A_2 B_2 C_2 + A_2 B_3 C_3) \\
& + (a_1 b_3 c_1 + a_2 b_3 c_2 + a_3 b_3 c_3) (A_3 B_1 C_1 + A_3 B_2 C_2 + A_3 B_3 C_3) \\
& + (a_2 b_1 c_1 + a_1 b_2 c_1 + a_1 b_1 c_2) (A_2 B_1 C_1 + A_1 B_2 C_1 + A_1 B_1 C_2) \\
& + (a_3 b_2 c_2 + a_2 b_3 c_2 + a_2 b_2 c_3) (A_3 B_2 C_2 + A_2 B_3 C_2 + A_2 B_2 C_3) = 0.
\end{aligned}$$

The work of expanding (29) is long and the result only will be indicated. It requires the summing of 6 terms like $(a_1 b_3 c_3 + a_3 b_2 c_3 + a_3 b_3 c_2) (2 a_1^2 b_2 c_2 c_3 + 2 a a_3 b_1 c_2 c_2 + 2 a a_2 b_3 c_1 c_1 - 2 a_1^2 b_2 c_3 c_2 - 2 a a_3 b_1 c_2 c_1 - 2 a a_2 b_3 c_1 c_2 + a_1^2 b_2^2 c_1 c_3 + a_1 a_3 b_2^2 c_1^2 + a_1^2 b_1 b_3 c_2^2 - a_1^2 b_1 b_3 c_1^2 - a_1 a_3 b_1^2 c_2^2 - a_1^2 b_2^2 c_1 c_3) = 0$.

Thus the identity is proved.

very concisely thus

$$\begin{aligned}
(30) & 2 \left(\sum a_1 a_2 a_3 b_1^2 b_3 c_1^2 c_3 - \sum a_1 a_2 a_3 b_1^2 b_3 c_2^2 c_3 \right) \\
& + 3 \left(\sum a_1 a_2^2 b_2^2 c_3 c_1^2 - \sum a_1 a_2^2 b_2^2 c_3 c_2^2 \right) \\
& + 2 \left(\sum a_1^3 b_2 b_3^2 c_2^2 c_3 - \sum a_1^3 b_2 b_3^2 c_1^2 c_3 \right) = 0
\end{aligned}$$

To express this in terms of the fundamental invariants, we observe first of all that $\sum a_1^3 b_2 b_3^2 c_2^2 c_3 = \sum a_1^3 b_2 b_3^2 c_1^2 c_3$

terms to a certain power. It can be seen that $D_1^3, I_1^2 D_1, I_1 I_2$ and $I_1^2 I_2$ are the only terms which can enter. Determining the coefficients is not hard.

(31) $D_1^3 - I_1^2 D_1 - 3 I_1 D_2 + 9 I_2 I_1 = 0.$

Hence the Theorem:

The two Clebschians of two triangles are apolar if

$$D_1^3 - I_1^2 D_1 - 3 I_1 D_2 + 9 I_2 I_1 = 0$$

This expression is also self dual as we should expect.

It can be used to give the invariants S' and T' of χ' , that is of the Clebschian arising from the dual equation. The equation of this line cubic has already been given (28) hence its invariants are known. The "dual" of the coefficients of χ , (27) it is evident that we can

reduces our class but is so that we
 have the equation of the circle is very
 long. But the truth of the statement can
 be understood from simply substituting the
 argument of g' which is not good.

§9. Self-dual Invariant Forms.

A number of self-dual forms have arisen in the course of this article, and the question naturally arises as to the number of such forms which are independent. These self-dual forms acquire special interest from the fact that the vanishing of such a form indicates a mutual relation between the two triangles. We shall look for the most general forms of the lower degree which are left unaltered by the dual transformation, to within a power of D_1 .

Of degree one, the only form is

1)

$$D_1.$$

For the form of degree two, the most general one is,

2)

$$aI_1 + bI_2 + cD_1 = \alpha L_1L_2 + cD_1^2.$$

That this equal the dual form, i.e.

$$\begin{aligned} D_1^2(aI_1^2 + bI_2 + cD_2 + dI_1D_1 + eD_1^2) \\ \equiv a(I_1^2D_1^2 - 12I_1D_1D_2 + 36D_2^2) \\ + b(I_1^2I_2 - 12I_1D_1D_2 + 6I_2^2) - cD_1^2D_2 \\ + dD_1^2(I_1D_1 - 6D_2) + eD_1^4. \end{aligned}$$

Equating coefficients, the equations of condition are

$$12a + 2b = 0 \quad b = b$$

$$36a + 6b = 0$$

$$-c - 6d = +c$$

$\therefore c = 3d$ and $b = -6a$ are the only restrictions. \therefore

$\therefore a(I_1^2 - 6I_2) + d(I_1D_1 - 3D_2) + eD_1^2 = 0$, is

the most general self-dual invariant form of the second degree, where a, d and e are arbitrary constants. Hence

(3). $I_1^2 - 6I_2$ and $I_1D_1 - 3D_2$ are the only two independent, irreducible self-dual invariants of degree 2. It may be noted that while $I_2 = 0$ expresses the

mutual relation, being one of the two mutual ones, it is not strictly self dual, for it changes sign under the dual transformation, hence could not be used in building up a pencil of self dual forms. D_2^2 is self dual.

For the most general cubic form we must have

$$\begin{aligned}
 (4) \quad I_1^3 & (a I_1^3 + b D_1^3 + c I_1^2 I_2 + d I_1 I_2^2 + e I_1 I_2 + f I_1 D_2 \\
 & + g D_1 D_2 + h I_2 D_1 + 2k I_3) \\
 & \equiv a (I_1^3 D_1^3 - 18 I_1^2 D_1^2 D_2 + 108 I_1 D_1 D_2^2 - 216 D_2^3) \\
 & + b D_1^6 + c D_1^2 (I_1^2 D_1^2 - 12 I_1 D_1 D_2 + 36 D_2^2) \\
 & + d (I_1 D_1^5 - 6 D_1^4 D_2) \\
 & + e (I_1 I_2 D_1^3 - 2 I_1^2 I_2 D_1 + 6 I_1 D_1 I_2^2 - 6 I_1^2 I_2 D_2 + 12 I_1 I_2 D_1^2 - 36 D_2^2) \\
 & + f (-I_1 D_1^3 D_2 + 6 D_1^4 D_2^2) - g (D_1^4 D_2) \\
 & + h (D_1^4 I_2 - 24 D_1^3 D_2 + 6 D_1^2 D_2^2) + k (2 D_1 I_3 - 2 D_1^3 + I_1 D_1 D_2^2 - I_2 D_1^2 D_2).
 \end{aligned}$$

Since a number of the equations of condition resulting from the above is superfluous, we need only consider those such as are distinct, they are



$$-12a - 2c = 0$$

$$a = -9c$$

$$108a + 18c + 12b = 0$$

$$b = 34c$$

$$36c + 6b + 6a = 0 \quad \text{or} \quad 6c = -(a+b)$$

$$-6d - g = g \quad \text{or} \quad g = -3d$$

Introducing these equalities in the left of (4) we have

$$g, 2(I_1^3 - 9I_1I_2 + 108I_3) + 2c(D_1^2 - 11D_2)$$

$$+ 2c(I_1I_2 - 6I_1D_1) + 6(I_1D_1 - I_1D_2),$$

the next general self dual invariant cubic form. We have here three independent cubics which are self dual

$$\text{I.} \quad I_1^3 - 9I_1I_2 + 108I_3.$$

$$\text{II.} \quad I_1^2D_1 - 6I_1D_2.$$

$$\text{III.} \quad I_2I_1 - I_1D_2.$$

It is well to consider the 6 simple self dual invariants we have derived: They are not independent, as we might suspect. For we should reasonably expect not more than five independent ones as our entire rational

system consisted of but six. Of course this does not insure that all self dual forms are expressible ^{rationaly} in terms of five. A distinct set of five is

$$A. \begin{cases} I_1; \\ I_1 D_1 - 6 I_2; & I_1^2 - 6 I_2; \\ I_2 D_1 - I_1 D_2; & I_1^3 - 9 I_1 I_2 + 108 I_3. \end{cases}$$

The other three forms on the last page can be expressed thus

$$I_1^2 D_1 - 6 I_1 D_2 = 6 (I_2 D_1 - I_1 D_2) + D_1 (I_1^2 - 6 I_2).$$

The most general self dual quartic invariant was found to be

$$a (I_1^4 - 12 I_1^2 I_2 + 36 I_2^2) + b (I_1 D_1 I_2 - 12 I_3 D_1 - 9 I_1^3 D_1) \\ + c (I_1^3 D_1 - 6 I_1 I_2 D_2) + d (I_1^2 D_1 - 6 I_1 I_2 D_2) \\ + e (D_1 I_2 - I_1 D_1 D_2) + f (I_1 D_1^3 - 3 D_1^2 D_2) + g D_2^2 + h D_1^4.$$

It turns out that all the several simple invariants making up the general form are expressible in terms of the 5 forms of A). I_1^4 seems at first to be an independent quartic

really covered by the general quartic

$$S = 4(I_1 D_1 - 3 D_2)^2 - (I_1^2 + D_1^2 - 6 I_2)^2 \\ = 4(I_1 D_1 - 3 D_2)^2 - [(I_1^2 - 6 I_2) + D_1^2]^2.$$

$$T = (I_1^2 - 6 I_2)^3 - 2 \cdot 6 I_1^2 (I_2^2 - 3 I_1 D_1 - 3 I_2 D_2) + 34(I_1^2 - 6 I_2)(I_1 D_1 - 3 D_2) \\ + 36 I_1^2 (I_2 D_1 - I_1 D_2) \\ = (I_1^2 - 6 I_2)^3 - D_1^6 - 3(I_1 D_1 - 3 I_2 D_2)^2 + 34(I_1 D_1 - 3 D_2)^2 \\ + 3(36 D_2^2 + I_1^4)(I_1^2 - 6 I_2) + 36 D_1^3 (I_2 D_1 - I_1 D_2) \\ + 108 D_1^2 D_2^2.$$

And since

$$9 D_2^2 = (I_1 D_1 - 3 D_2)^2 - 6 D_1 (I_1 D_1 - 3 I_2 D_2) - D_1^2 (I_1^2 - 6 I_2)$$

$$+ I_1 D_1 - 6 I_2 D_2 = 6(I_2 D_1 - I_1 D_2) + D_1 (I_1^2 - 6 I_2)$$

we have in terms of our first form

$$T = (I_1^2 - 6 I_2)^3 - D_1^6 - 162(I_2 D_1 - I_1 D_2)^2 - 18 D_1^2 (I_1^2 - 6 I_2)^2 \\ - 108(I_2 D_1 - I_1 D_2) D_1 (I_1^2 - 6 I_2) + 12(I_1 D_1 - 3 D_2)^2 (I_1^2 - 6 I_2) \\ - 36 D_1^3 (I_2 D_1 - I_1 D_2) + 12 D_1^2 (I_1 D_1 - 3 D_2)^2 - 9 D_1^4 (I_1^2 - 6 I_2).$$

This might be grouped more compactly but it establishes the point aimed at. It thus turns out that all self dual forms

arising are found to be rational functions of these five.

If an invariant form is self-dual it is naturally of peculiar interest. Unfortunately, however, the simpler self-dual forms of the form above treated are the only of that kind, present a simple geometric interpretation.

$$D_1 = H_1$$

$$I_1 D_1 - 3 D_2 = H_2$$

$$I_2 D_1 - I_1 D_2 = H_3$$

$$I_1^2 - 6 I_2 = K_2$$

$$I_1^3 - 9 I_1 I_2 + 108 I_3 = K_3$$

$$D_1 = H_1$$

$$-3 D_2 = H_2 - I_1 H_1$$

$$-6 I_2 = K_2 - I_1^2$$

$$108 I_3 = K_3 - \frac{3}{2} I_1 K_2 + \frac{1}{2} I_1^3$$

$$\text{From } * \quad I_1^2 H_1 - 2 H_2 I_1 = -H_3 + H_1 K_2$$

Hence any self dual invariant by multiplication with a power of H_1 can be changed into an invariant of the form $S_1 + I_1 S_2 \equiv I$ where S_1 and S_2 are functions of the self dual invariants H_1, H_2, K_2, H_3, K_3

Since I, S_1, S_2 and $S_1 + I_1 S_2$ are all self dual while I_1 is not, S_2 must vanish and I is a function of H, H_2, K_2, H_3, K_3 also. Hence these five self dual invariants are a complete system of self dual invariants

§ 10. The Fundamental Invariants under a Special Cremona Trans- formation.

It is the purpose here to show the changes produced in the fundamental invariants, by carrying out a special Cremona transformation, and to illustrate by a single example the value of this knowledge.

Take the simple, quadratic involutory transformation

$$y_i = \frac{1}{x_i}.$$

The effect of this transformation is to replace each symbol in the invariant by its reciprocal. Since all invariant forms are homogeneous, it is clear that the same power of k appears in each term, hence can be dropped without loss of generality.

Carrying out this transformation on the fundamental invariants

$$B. \begin{cases} D_1' = \frac{D_2}{I_3} & I_2 = \frac{I_1}{I_3} \\ D_2' = \frac{D_1}{I_3} & I_3 = \frac{1}{I_3} \\ I_1 = \frac{I_2}{I_3} \end{cases}$$

As a typical illustration we take the rational quartic which we can write parametrically as

$$x_i = \frac{t - \alpha_i}{(t - \beta_i)^2}$$

which has 3 cusps, 3 double points, 3 double tangents, 3 flexes and is of class 5, and which has been the subject of considerable study. It can be shown by the simple counting of constants that any two of the singular triangles are not independent, but have a correspondence connecting them. Hence taking any one triangle of double points as our reference 5-triad, we write

ask, what is the relation between the triangle of cusps?

From the theory of Bézout's transformations,* it is well known that if the above involutory transformation is carried out on the quartic curve, taking the double points as fundamental points, the quartic goes into a rational quartic with three cusps, and has no cusp points at the three fundamental points. If we now carry out the same transformation regarding the cusps as fundamental points (which is itself equivalent to taking the dual) the rational quartic goes into a conic, which touches the fundamental lines, and has the three cusp points for ordinary points. But we already

* Clebsch - Leçons - Vol II, page 192 ff.

from previous chapter the condition that a triangle be inscribed in the 3-line and circumscribed about the 3-point. It is

$$(1). (D_1^4 - 8D_1^2 I_2 + 16D_2^2)^2 - 512 I_3 D_1^3 (I_1 D_1 - 4D_2) = 0.$$

Hence to find the condition on the cusp triangles we must take (1) and carry out in reverse order the transformations we carried out on the curves. That is first carry out transformation (B) of this section, then the dual transformation of the previous chapter, and finally transformation (B), again. This gives a rather long expression of the 24th degree in the coefficients of the original triangles. So the relation is probably not a very simple one geometrically.

If we take the dual of the cusp triangles we get as far as the relation

3-line), the condition on the 3-point of double points turns out to be of the 11th degree by a similar argument as assumed this form

$$D_1^6 D_2^{5-} + (16 I_1 D_1^2 D_2 - 64 I_1 D_1 D_2^2 + 64 D_2^3 - 16 D_1^4 D_2 - 256 I_3 D_1^3) \\ (2 D_1^3 I_3 - 2 D_2^3 + I_1 D_1 D_2^2 - I_2 D_1^2 D_2)^2 \\ - D_2 (16 I_1 D_1^6 D_2 - 24 I_1 D_1^4 D_2^2 + 4 D_1^4 D_2^3) (2 D_1 I_3 - 2 D_2^3 + I_1 D_1 D_2^2 - I_2 D_1^2 D_2) = 0.$$

This is sufficient to illustrate our point. For by a direct attack this problem would have been impossible, yet by aid of this transformation it is comparatively simple. Other examples might be carried out to still further illustrate this.

Incidentally this gives me a convenient geometrical interpretation of $I_2 = 0$. For if we carry out the transformation $y_i = \frac{1}{x_i}$ on the coordinates of my 3-point. They are carried into three new points whose equations are

$$a_2 a_3 \xi_1 + a_3 a_1 \xi_2 + a_1 a_2 \xi_3 = 0$$

$$b_2 b_3 \xi_1 + b_3 b_1 \xi_2 + b_1 b_2 \xi_3 = 0$$

$$c_2 c_3 \xi_1 + c_3 c_1 \xi_2 + c_1 c_2 \xi_3 = 0$$

and thereby the condition that there be a polar to the reference triangle is $I_1 = 0$. This is a definite theorem:

If two triangles are such that when one is taken as a three-line and the other as a three-point, and the transformation $\xi_i \rightarrow \frac{1}{\xi_i}$ is carried out, the three point is a polar to the three line, then

$$I_2 = 0.$$

Of course this gives no direct confirmation as to the geometrical relations between the two triangles in their original position.

Vita.

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and courses under Professors
Morley, Cohen, Coble, Hitchcock
and Reid. To each of these he
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